

Match-up database Analyses Report

SMOS-L3-CATDS-CECOS-LOCEAN-V3- 18DAYS-25KM

Argo

South Atlantic Ocean

prepared by the Pi-MEP Consortium October 15, 2018

Contents

List of Figures

Acronym

1 Overview

In this report, we present systematic analyses of the Match-up DataBase (MDB) files generated by the Pi-MEP platform within the following Pi-MEP region and for the below pair of Satellite/In situ SSS data:

- Pi-MEP region: South Atlantic Ocean (download the corresponding mask [here\)](https://pimep.ifremer.fr/diffusion/mask/pimep-region_SAO.nc)
- SSS satellite product (SSS_{SAT}) : SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM
- In situ dataset (SSS_{Insitu}) : Argo (download the corresponding report [here\)](https://pimep.ifremer.fr/diffusion/analyses/insitu-database/report/pimep-insitu-report_argo_20181015.pdf)

In the following, $\Delta SSS = SSS_{SAT} - SSS_{Institu}$ denotes the difference between the satellite and in situ SSS at the colocalized points that form the MDB.

This report presents successively:

The MDB file DataSets (Section [2\)](#page-5-0)

- A short description of the satellite SSS product considered in the match-up [\(2.1\)](#page-5-1)
- A short description of the In situ SSS dataset considered in the match-up [\(2.2\)](#page-5-3)
- A short description of the auxiliary geophysical datasets co-localized with SSS pairs [\(2.3\)](#page-6-0)
- An overview of how the Match-ups were evaluated (2.4)
- An overview of the MDB characteristics for the particular in situ/satellite pairs [\(2.5\)](#page-15-0)

The major results of the MDB file Analyses (Section [3\)](#page-17-1)

- Spatial Maps of the Time-mean and temporal STD of in situ and satellite SSS and of the Δ SSS [\(3.1\)](#page-17-2)
- Time series of the monthly averaged mean and STD of in situ and satellite SSS and of the \triangle SSS [\(3.2\)](#page-18-0)
- Zonally-averaged Time-mean and temporal STD of in situ and satellite SSS and of the $\triangle SSS(3.3)$ $\triangle SSS(3.3)$
- Scatterplots of satellite vs in situ SSS by latitudinal bands [\(3.4\)](#page-21-0)
- Time series of the monthly averaged mean and STD of the ∆SSS sorted by latitudinal bands (3.5)
- Δ SSS sorted as function of geophysical conditions [\(3.6\)](#page-22-1)

All analyses are conducted over the Pi-MEP Region specified above and over the full satellite SSS product period.

2 The MDB file datasets

2.1 Satellite SSS product

2.1.1 SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM

In order to propose improved methodologies to be implemented in the near real time CATDS processing chain (CATDS-CPDC), LOCEAN/IPSL (UMR CNRS/UPMC/IRD/MNHN) and ACRIst have derived a methodology for correcting systematic SSS biases. The v3 release uses an improved 'debiasing' technique [\(Boutin et al.](#page-27-0) [\(2018\)](#page-27-0)) and the adjustment of the long term mean SMOS SSS in very dynamical areas, like in river plumes, and the bias correction at high latitudes have been improved.

Maps are provided every 4 days from 01/2010 to 12/2017 and are derived from a combination of ascending and descending orbits. Debiased SSS are temporally averaged using a slipping Gaussian kernel with a full width at half maximum of 18 days (18 day product). Maps are at a spatial resolution 25x25km2 and a median filtering over nearest neighbors is applied.

The [L3 DEBIAS LOCEAN v2](http://www.catds.fr/Products/Available-products-from-CEC-OS/L3-Debiased-Locean-v2) Sea Surface Salinity product [\(Boutin et al.](#page-27-1) [\(2017\)](#page-27-1)) have been produced by LOCEAN/IPSL (UMR CNRS/UPMC/IRD/MNHN) laboratory and ACRI-st company and is distributed by the Ocean Salinity Expertise Center (CEC-OS) of the CNES-IFREMER Centre Aval de Traitement des Donnees SMOS (CATDS), at IFREMER, Plouzane (France).

SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM					
Spatial resolution	$25 \;{\rm km}$				
Temporal resolution	18 days (file every 4 days)				
Temporal coverage	From 2010-01-16 to 2017-12-26				
Data Provider	CATDS				
Release Date	2018-07				
Version					
Data access	debiasedSSS_18days_v3				
DOI	http://doi.org/10.17882/52804				
Documentation	Doc_L3_DEBIAS_LOCEAN_v3.pdf				

Table 1: Satellite SSS product characteristics

2.2 In situ SSS dataset

Argo is a global array of 3,000 free-drifting profiling floats that measures the temperature and salinity of the upper 2000 m of the ocean. This allows, for the first time, continuous monitoring of the temperature and salinity of the upper ocean, with all data being relayed and made publicly available within hours after collection. The array provides around 100,000 temperature/salinity profiles per year distributed over the global oceans at an average of 3-degree spacing. Only Argo salinity and temperature float data with quality index set to 1 or 2 are kept. Argo floats appearing in the [grey list](ftp://ftp.ifremer.fr/ifremer/argo/ar_greylist.txt) are discarded and, real time (RT), real time adjusted (RTA) and delayed mode (DM) are considered for the test period of the Pi-MEP. The upper ocean salinity and temperature values recorded between 0m and 10m depth are considered as Argo sea surface salinities (SSS) and sea surface temperatures (SST). These data were collected and made freely available by the international Argo project and the national programs that contribute to it [\(Argo](#page-27-2) (2000)).

2.3 Auxiliary geophysical datasets

Additional EO datasets are used to characterize the geophysical conditions at the in situ/satellite SSS pair measurement locations and time, and 10 days prior the measurements to get an estimate of the geophysical condition and history. As discussed in [Boutin et al.](#page-27-3) [\(2016\)](#page-27-3), the presence of vertical gradients in, and horizontal variability of, sea surface salinity indeed complicates comparison of satellite and in situ measurements. The additional EO data are used here to get a first estimates of conditions for which L-band satellite SSS measured in the first centimeters of the upper ocean within a 50-150 km diameter footprint might differ from pointwise in situ measurements performed in general between 10 and 5 m depth below the surface. The spatiotemporal variability of SSS within a satellite footprint (50–150 km) is a major issue for satellite SSS validation in the vicinity of river plumes, frontal zones, and significant precipitation. Rainfall can in some cases produce vertical salinity gradients exceeding 1 pss m^{-1} ; consequently, it is recommended that satellite and in situ SSS measurements less than 3–6 h after rain events should be considered with care when used in satellite calibration/validation analyses. To identify such situation, the Pi-MEP test platform is first using [CMORPH](#page-6-1) products to characterize the local value and history of rain rate and [ASCAT](#page-7-0) gridded data are used to characterize the local surface wind speed and history. For validation purpose, the [ISAS](#page-7-1) monthly SSS in situ analysed fields at 5 m depth are collocated and compared with the satellite SSS products. The use of ISAS is motivated by the fact that it is used in the SMOS L2 official validation protocol in which systematic comparisons of SMOS L2 retrieved SSS with ISAS are done. In complement to ISAS, monthly std climatological fields from the World Ocean Atlas [\(WOA13\)](#page-8-0) at the match-up pairs location and date are also used to have an a priori information of the local SSS variability.

2.3.1 CMORPH

Precipitation are estimated using the [CMORPH](http://www.cpc.ncep.noaa.gov/products/janowiak/cmorph_description.html) 3-hourly products at 1/4[°] resolution [\(Joyce](#page-28-0) [et al.](#page-28-0) [\(2004\)](#page-28-0)). CMORPH (CPC MORPHing technique) produces global precipitation analyses at very high spatial and temporal resolution. This technique uses precipitation estimates that have been derived from low orbiter satellite microwave observations exclusively, and whose features are transported via spatial propagation information that is obtained entirely from geostationary satellite IR data. At present NOAA incorporate precipitation estimates derived from the passive microwaves aboard the DMSP 13, 14 and 15 (SSM/I), the NOAA-15, 16, 17 and 18 (AMSU-B), and AMSR-E and TMI aboard NASA's Aqua, TRMM and GPM spacecraft, respectively. These estimates are generated by algorithms of [Ferraro](#page-28-1) [\(1997\)](#page-28-1) for SSM/I, [Ferraro](#page-28-2) [et al.](#page-28-2) [\(2000\)](#page-28-2) for AMSU-B and [Kummerow et al.](#page-28-3) [\(2001\)](#page-28-3) for TMI. Note that this technique is not a precipitation estimation algorithm but a means by which estimates from existing microwave rainfall algorithms can be combined. Therefore, this method is extremely flexible such that any precipitation estimates from any microwave satellite source can be incorporated.

With regard to spatial resolution, although the precipitation estimates are available on a grid with a spacing of 8 km (at the equator), the resolution of the individual satellite-derived estimates is coarser than that - more on the order of 12 x 15 km or so. The finer "resolution" is obtained via interpolation.

In effect, IR data are used as a means to transport the microwave-derived precipitation features during periods when microwave data are not available at a location. Propagation vector matrices are produced by computing spatial lag correlations on successive images of geostationary satellite IR which are then used to propagate the microwave derived precipitation estimates. This process governs the movement of the precipitation features only. At a given location, the shape and intensity of the precipitation features in the intervening half hour periods between microwave scans are determined by performing a time-weighting interpolation between microwave-derived

features that have been propagated forward in time from the previous microwave observation and those that have been propagated backward in time from the following microwave scan. NOAA refer to this latter step as "morphing" of the features.

For the present Pi-MEP products, we only considered the 3-hourly products at 1/4 degree resolution. The entire CMORPH record (December 2002-present) for 3-hourly, 1/4 degree lat/lon resolution can be found at: [ftp://ftp.cpc.ncep.noaa.gov/precip/CMORPH_V1.](ftp://ftp.cpc.ncep.noaa.gov/precip/CMORPH_V1.0/RAW/) [0/RAW/](ftp://ftp.cpc.ncep.noaa.gov/precip/CMORPH_V1.0/RAW/). CMORPH estimates cover a global belt (-180◦W to 180◦E) extending from 60◦S to 60◦N latitude and are available for the complete period of the Pi-MEP core datasets (Jan 2010-now).

2.3.2 ASCAT

Advanced SCATterometer (ASCAT) daily data produced and made available at [Ifremer/CERSAT](ftp://ftp.ifremer.fr/ifremer/cersat/products/gridded/MWF/L3/ASCAT/Daily/Netcdf/) on a 0.25°x0.25° resolution grid [\(Bentamy and Fillon](#page-27-4) [\(2012\)](#page-27-4)) since March 2007 are used to characterize the mean daily wind at the match-up pair location as well as the wind history during the 10-days period preceding the in situ measurement date. These wind fields are calculated based on a geostatistical method with external drift. Remotely sensed data from ASCAT are considered as observations while those from numerical model analysis (ECMWF) are associated with the external drift. The spatial and temporal structure functions for wind speed, zonal and meridional wind components are estimated from ASCAT retrievals. Furthermore, the new procedure includes a temporal interpolation of the retrievals based on the complex empirical orthogonal function (CEOF) approach, in order to enhance the sampling length of the scatterometer observations. The resulting daily wind fields involves the main known surface wind patterns as well as some variation modes associated with temporal and spatial moving features. The accuracy of the gridded winds was investigated through comparisons with moored buoy data in [Bentamy](#page-27-5) [et al.](#page-27-5) [\(2012\)](#page-27-5) and resulted in rms differences for wind speed and direction are about 1.50 m.s–1 and 20° .

2.3.3 ISAS

The In Situ Analysis System (ISAS), as described in [Gaillard et al.](#page-28-4) [\(2016\)](#page-28-4) is a data based re-analysis of temperature and salinity fields over the global ocean. It was initially designed to synthesize the temperature and salinity profiles collected by the ARGO program. It has been later extended to accommodate all type of vertical profile as well as time series. ISAS gridded fields are entirely based on in-situ measurements. The methodology and configuration have been conceived to preserve as much as possible the data information content and resolution. ISAS is developed and run in a research laboratory (LOPS) in close collaboration with Coriolis, one of ARGO Global Data Assembly Center and unique data provider for the Mercator operational oceanography system. At the moment the period covered starts in 2002 and only the upper 2000m are considered. The gridded fields were produced over the global ocean 70◦N–70◦S on a 1/2◦ grid by the ISAS project with datasets downloaded from the Coriolis data center (for more details on ISAS see [Gaillard et al.](#page-28-5) [\(2009\)](#page-28-5)). In the PiMEP, the product in used is the INSITU GLO TS OA NRT [OBSERVATIONS](http://marine.copernicus.eu/services-portfolio/access-to-products/?option=com_csw&view=details&product_id=INSITU_GLO_TS_OA_NRT_OBSERVATIONS_013_002_a) 013 002 a v6.2 NRT derived at the Coriolis data center and provided by Copernicus ([www.marine.copernicus.eu/documents/](www.marine.copernicus.eu/documents/PUM/CMEMS-INS-PUM-013-002-ab.pdf) [PUM/CMEMS-INS-PUM-013-002-ab.pdf](www.marine.copernicus.eu/documents/PUM/CMEMS-INS-PUM-013-002-ab.pdf)). The major contribution to the data set is from Argo array of profiling floats, reaching an approximate resolution of one profile every 10-days and every 3-degrees over the Satellite SSS period ([http://www.umr-lops.fr/SNO-Argo/Products/](http://www.umr-lops.fr/SNO-Argo/Products/ISAS-T-S-fields/) [ISAS-T-S-fields/](http://www.umr-lops.fr/SNO-Argo/Products/ISAS-T-S-fields/)); in this version SSS from thermosalinographs from ship of opportunity are not used, so that we can consider SMOS SSS validation using ship of opportunity measurements independent of ISAS. The ISAS optimal interpolation involves a structure function modeled as the sum of two Gaussian functions, each associated with specific time and space scales, resulting

in a smoothing over typically 3 degrees. The smallest scale which can be retrieved with ISAS analysis is not smaller than 300–500 km [\(Kolodziejczyk et al.](#page-28-6) [\(2015\)](#page-28-6)). For validation purpose, the ISAS monthly SSS fields at depth level 5 m are collocated and compared with the satellite SSS products and included in the PIMEP MDB files. In addition, the \leq percentage of variance fields (PCTVAR) contained in the ISAS analyses provide information on the local variability of in situ SSS measurements within $1/2°x1/2°$ boxes.

2.3.4 World Ocean Atlas Climatology

The World Ocean Atlas 2013 version 2 [\(WOA13 V2\)](https://www.nodc.noaa.gov/OC5/woa13/) is a set of objectively analyzed (1◦ grid) climatological fields of in situ temperature, salinity and other variables provided at standard depth levels for annual, seasonal, and monthly compositing periods for the World Ocean. It also includes associated statistical fields of observed oceanographic profile data interpolated to standard depth levels on 5° , 1°, and 0.25° grids. We use these fields in complement to ISAS to characterize the climatological fields (monthly mean and std) at the match-up pairs location and date.

2.4 Overview of the Match-ups generation method

The match-up production is basically a three steps process:

- 1. preparation of the input in situ and satellite data, and,
- 2. co-localization of satellite products with in situ SSS measurements.
- 3. co-localization of the in situ/satellite pair with auxiliary information.

In the following, we successively detail the approaches taken for these different steps.

2.4.1 In Situ/Satellite data filtering

The first step consist in filtering Argoin situ dataset using the quality flags as described in [2.2](#page-5-3) so that only valid salinity data remains in the produced match-ups.

For high-spatial resolution in situ SSS measurements such as the Thermo-SalinoGraph (TSG) SSS data from research vessels, Voluntary Observing Ships (VOS) or sailing ships, as well as SSS data from surface drifters, an additional spatial-filtering step is performed on the in situ data that will be in fine compared to the satellite SSS products. If R_{sat} is the spatial resolution of the satellite SSS product (L2 to L3-L4), we keep the in situ data at the original spatial resolution but we also estimate for all spatio-temporal samples a running median filtered SSS applied to all neighbouring in situ SSS data acquired within a distance of $R_{sat}/2$ from a given in situ acquisition. Both the original and the filtered data are finally stored in the MDB files.

Only for satellite L2 SSS data, a third step consist in filtering spurious data using the flags and associated recommendation as provided by the official data centers and described in [2.1.](#page-5-1)

2.4.2 In Situ/Satellite Co-localization

In this step, each SSS satellite acquisition is co-localized with the filtered in situ measurements. The method used for co-localization differ if the satellite SSS is a swath product (so-called Level 2-types) or a time-space composite product (so-called Level 3/level 4-types).

• For L2 SSS swath data :

If R_{sat} is the spatial resolution of the satellite swath SSS product, for each in situ data sample collected in the Pi-MEP database, the platform searches for all satellite SSS data found at grid nodes located within a radius of $R_{sat}/2$ from the in situ data location and acquired with a time-lag from the in situ measurement date that is less or equal than \pm 6 hours. If several satellite SSS samples are found to meet these criteria, the final satellite SSS match-up point is selected to be the closest in time from the in situ data measurement date. The final spatial and temporal lags between the in situ and satellite data are stored in the MDB files.

• For L3 and L4 composite SSS products :

If R_{sat} is the spatial resolution of the composite satellite SSS product and D the period over which the composite product was built (e.g., periods of 1, 7, 8, 9, 10, 18 days, 1 month, etc..) with central time to, for each in situ data sample collected in the Pi-MEP database during period D, the platform searches for all satellite SSS data of the composite product found at grid nodes located within a radius of $R_{sat}/2$ from the in situ data location. If several satellite SSS product samples are found to meet these criteria, the final satellite SSS match-up point is chosen to be the composite SSS with central time to which is the closest in time from the in situ data measurement date. The final spatial and temporal lags between the in situ and satellite data are stored in the MDB files.

2.4.3 MDB pair Co-localization with auxiliary data and complementary information

MDB data consist of satellite and in-situ SSS pair datasets but also of auxiliary geophysical parameters such as local and history of wind speed and rain rates, as well as various information (climatology, distance to coast, mixed layer depth, barrier layer thickness, etc) that can be derived from in situ data and which are included in the final match-up files. The collocation of auxiliary parameters and additional information is done for each filtered in-situ SSS measurement contained in the match-up files as follows :

If t_{insitu} is the time/date at which the in situ measurement is performed, we collect:

- The [ASCAT](#page-7-0) wind speed product of the same day than t_{insitu} found at the ASCAT 1/4 \circ grid node with closest distance from the in situ data location and the time series of the ASCAT wind speed at the same node for the 10 days prior the in situ measurement day.
- If the in situ data is located within the 60◦N-60◦S band, we select the [CMORPH](#page-6-1) 3-hourly product the closest in time from tin situ and found at the CMORPH $1/4°$ grid node with closest distance from the in situ data location. We then store the time series of the CMORPH rain rate at the same node for the 10 days prior the in situ measurement time.

For the given month/year of the in situ data, we select the [ISAS](#page-7-1) and [WOA](#page-8-0) fields for the same month (and same year for ISAS fields) and take the SSS analysis (monthly mean, std) found at the grid node the closest from the in situ measurement.

The distance from the in situ SSS data location to the nearest coast is evaluated and provided in kms. We use a distance-to-coast map derived by CLS with a spatial resolution of $1/16°$ that we re-gridded at $1/4°$ resolution taking the minimum value of all $1/16°$ observations found in the $1/4^\circ$ grid cell.

When vertical profiles of S and T are made available from the in situ measurements used to build the match-up (Argo or sea mammals), the following variables are included into each satellite/in situ match-up file:

- 1. The vertical distribution of pressure at which the profile were measured,
- 2. The vertical $S(z)$ and $T(z)$ profiles,
- 3. The vertical potential density anomaly profile $\sigma_0(z)$,
- 4. The Mixed Layer Depth (MLD). The MLD is defined here as the depth where the potential density has increased from the reference depth (10 meter) by a threshold equivalent to 0.2◦C decrease in temperature at constant salinity: $\sigma_0 = \sigma_{010m} + \Delta \sigma_0$ with $\Delta \sigma_0 = \sigma_0(\theta_{10m} (0.2, S_{10m}) - \sigma_0(\theta_{10m}, S_{10m})$ where θ_{10m} and S_{10m} are the temperature and salinity at the reference depth (i.e. 10 m) (de Boyer Montégut et al. [\(2004\)](#page-27-6), de Boyer Montégut et al. (2007)).
- 5. The Top of the Thermocline Depth (TTD) is defined as the depth at which temperature decreases from its 10 m value by 0.2◦C.
- 6. The Barrier Layer if present, is defined as the intermediate layer between the top of the thermocline and the bottom of the density mixed-layer and its thickness (BLT) is defined as the difference between the MLD and the TTD.
- 7. The vertical profile of the buoyancy frequency $N^2(z)$

The resulting match-ups files are serialized as NetCDF-4 files whose structure depends on the origin of the in-situ data they contain.

2.4.4 Content of the Match-Up NetCDF files

netcdf pimep-mdb smos-l3-catds-locean-v3-18d argo TIMEID v01 { dimensions: $N₋prof = 944$; N LEVELS = 499; N -DAYS-WIND = 10; $N_3H_RAIN = 80$; TIME $Sat = UNLIMITED$; // (1 currently) variables: float DATE_ARGO(N_prof); DATE ARGO:long name = "Date of Argo profile" ; $\text{DATE}_\text{ARGO:units} = "days \text{ since } 1990-01-01 \text{ } 00:00:00"$; $\text{DATE}_\text{ARGO:standard}_\text{name} = "time"$; DATE_ARGO: FillValue = -999.f; float LATITUDE_ARGO(N_prof); LATITUDE $\triangle RGO: long_name = "Latitude of Argo profile"$; $LATITUDE_ARGO:units = "degrees.north" ;$ LATITUDE_ARGO:valid_min = $-90.$; LATITUDE_ARGO:valid_max = $90.$; $\text{LATITUDE}_\text{ARGO:standard_name} = \text{"lattice"}$; LATITUDE_ARGO:_FillValue = $-999.f$; float LONGITUDE_ARGO(N_prof); LONGITUDE ARGO:long name = "Longitude of Argo profile" ; $LONGITUDE_ARGO:units = "degrees_east" ;$ $LONGITUDE_{ARGO}:valid_{min} = -180.$ $LONGITUDE_ARGO:valid_max = 180.$;

LONGITUDE ARGO:standard name = "longitude" ; $LONGITUDE_ARGO:$ -FillValue = -999.f; float SSS_DEPTH_ARGO(N_prof); SSS_DEPTH_ARGO:long_name $=$ "Sea water pressure at Argo float location (equals 0 at sea level)" ; SSS -DEPTH-ARGO:units = "decibar" ; SSS DEPTH ARGO:standard name = "sea water pressure" ; SSS_DEPTH_ARGO:_FillValue = -999.f; float $SSS\text{-}ARGO(N\text{-}\text{prof})$; SSS ARGO:long name $=$ "Argo SSS" ; $SSS_\text{ARGO:units} = "1"$; $SSS \, ARGO: \, salinity \, scale = "Practical\, \, Salinity\, \, Scale (PSS-78)"$: $SSS_ARGO: standard_name = "sea_water_sality"$; $SSS_ARGO: FillValue = -999.f;$ float $SST_A RGO(N_{\text{--}})$; $SST_ARGO:long_name = "ArgO SST"$; $SST_ARGO:units = "degree Celsius"$; $SST_A RGO: standard_name = "sea_water_ttemperature"$; $SST_ARGO:$ FillValue = -999.f; float DELAYED_MODE_ARGO(N_prof); DELAYED_MODE_ARGO:long_name = "Argo data mode (delayed mode = 1, real time =0)" ; $DELAYED_MODE_ARGO:units = "1"$; DELAYED MODE ARGO: FillValue = -999.f ; float DISTANCE_TO_COAST_ARGO(N_prof); DISTANCE TO COAST ARGO:long name = "Distance to coasts at Argo float location"; $\label{eq:discrete} \text{DISTANCE_TO_COAST_ARGO: units} = "km"~;$ DISTANCE TO COAST ARGO: FillValue = -999.f ; float PLATFORM_NUMBER_ARGO(N_prof); PLATFORM_NUMBER_ARGO:long_name = "Argo float unique identifier" ; PLATFORM NUMBER ARGO:conventions = "WMO float identifier : A9IIIII" ; PLATFORM_NUMBER_ARGO:units = "1"; PLATFORM NUMBER ARGO: FillValue = -999.f ; float PSAL_ARGO(N_prof, N_LEVELS); $PSAL_ARGO:long_name = "Areo salinity profile"$: $PSAL_ARGO:units = "1"$: PSAL ARGO:salinity scale = "Practical Salinity Scale (PSS-78)" ; PSAL ARGO:standard name = "sea water salinity" ; $PSAL_ARGO:$ FillValue = $-999.$ f ; float TEMP_ARGO(N_prof, N_LEVELS); $TEMP_ARGO:long_name = "Argo temperature profile" ;$ $TEMP_ARGO:units = "degree Celsius"$; $TEMP_ARGO: standard_name = "sea_water_ttemperature"$; TEMP_ARGO:_FillValue = $-999.f$; float PRES_ARGO(N_prof, N_LEVELS); PRES ARGO:long name = "Argo pressure profile" ; PRES_ARGO:units = "decibar" ; PRES_ARGO:standard_name = "sea_water_pressure" ; PRES_ARGO:_FillValue = -999.f; float RHO_ARGO(N_prof, N_LEVELS);

 $RHO_ARGO:long_name = "Argo in-situ density profile"$; $RHO_ARGO:units = "kg/m"$; $RHO_ARGO:$ FillValue = $-999.$ f ; float SIGMA0_{-ARGO}(N_{-prof, N₋LEVELS);} $SIGMA0 \text{-} ARGO: \text{long_name} = "Argo potential density anomaly profile"$; $SIGMA0 \text{-} ARGO: units = "kg/m^{3"};$ $SIGMA0_ARGO:$ FillValue = -999.f; float N2_ARGO(N_prof, N_LEVELS); $N2$ _{ARGO}: long name $=$ "Argo buoyancy frequency profile" ; $N2$ _{-ARGO}:units = $1/s²$; $N2 \,\text{ARGO:}$ FillValue = -999.f; float $MLD \, ARGO(N \text{-} prof)$; MLD ARGO:long name = "Mixed Layer Depth (MLD) calculated from Argo profile (depth where $\sigma_0 = \sigma_{010m} + \Delta \sigma_0$ with $\Delta \sigma_0 = \sigma_0(\theta_{10m} - 0.2, S_{10m}) - \sigma_0(\theta_{10m}, S_{10m})$ "; $MLD_{ARGO:units} = "m"$; MLD _{-ARGO}: FillValue = -999.f; float TTD_ARGO(N_prof); TTD ARGO:long name = "Top of Thermocline Depth (TTD) calculated from Argo profile (depth where $\theta = \theta_{10m} - 0.2$)"; TTD_ARGO:units = $"m"$; $TTD_A RGO: FillValue = -999. f$; float $BLT_A RGO(N_{\text{--}})$; BLT ARGO:long name = "Barrier Layer Thickness (TTD-MLD)" ; $BLT _ARGO:units = "m"$; $BLT_A RGO:$ FillValue = $-999.f$; float DATE Satellite product (TIME Sat); DATE_Satellite_product:long_name = "Central time of satellite SSS file"; DATE_Satellite_product:units = $"days since 1990-01-01 00:00:00"$; DATE Satellite product:standard name = "time" ; float LATITUDE_Satellite_product(N_prof); LATITUDE Satellite product: \log_{10} name = "Satellite product latitude at Argo float location" ; $LATITUDE_Satellite_product:units = "degrees_north" ;$ LATITUDE_Satellite_product:valid_min = -90. ; LATITUDE Satellite product:valid $max = 90$. LATITUDE_Satellite_product:standard_name = "latitude" ; LATITUDE_Satellite_product:_FillValue = $-999.f$; float $LONGITUDE_Satellite-product(N_prof)$; LONGITUDE Satellite product: \log_{10} name = "Satellite product longitude at Argo float location" ; $\text{LONGITUDE_Satellite_product: units} = "degrees_east" ;$ LONGITUDE Satellite product:valid min $= -180$. LONGITUDE Satellite product:valid max $= 180$. $\textsc{LONGITUDE_Satellite-product:} \texttt{standard_name} = \text{"longitude"}~;$ $LONGITUDE_Satellite-product:$ FillValue = -999.f; float SSS_Satellite_product(N_prof); SSS_Satellite_product:long_name = "Satellite product SSS at Argo float location" ; SSS_Satellite_product:units = $"1"$; SSS Satellite product:salinity scale = "Practical Salinity Scale(PSS-78)" ; SSS -Satellite-product:standard name = "sea_surface_salinity" ;

SSS Satellite product: FillValue = -999.f ; float $SST_Satellite_product(N_prof)$; SST Satellite product:long name = "Satellite product SST at Argo float location" ; $SST_Satellite_product:units = "degree Celsius" ;$ SST_Satellite_product:standard_name = "sea_surface_temperature" ; SST Satellite product: FillValue = -999.f ; float $Spatial_lass(N_prof)$; Spatial lags:long name = "Spatial lag between Argo float location and satellite SSS product pixel center" ; Spatial lags: units $=$ " km "; $Spatial_lags: FillValue = -999.f;$ float $Time\text{lags}(N\text{-prof})$; Time lags:long name = "Temporal lag between Argo float time and satellite SSS product central time": $Time _ \text{lags:units} = "davs"$: Time_lags:_FillValue = $-999.f$; float ROSSBY_RADIUS_at_ARGO(N_prof); ROSSBY RADIUS at ARGO:long name = "Baroclinic Rossby radius of deformation (Chelton et al., 1998) at Argo float location" ; $ROSSBY_RADIUS_at_ARGO:units = "km" ;$ ROSSBY RADIUS at ARGO: FillValue = -999.f ; float Ascat_daily_wind_at_ARGO(N_prof); Ascat daily wind at ARGO:long name = "Daily Ascat wind speed module at Argo float location" ; Ascat_daily_wind_at_ARGO:units = $\mathrm{m/s}$ "; Ascat daily wind at ARGO: FillValue = -999.f ; float CMORPH_3h_Rain_Rate_at_ARGO(N_prof); CMORPH 3h Rain Rate at ARGO:long name = "3-hourly CMORPH rain rate at Argo float location" ; $CMORPH_3h_Rain_Rate_at_ARGO:units = "mm/3h" ;$ $CMORPH_3$ h Rain Rate at ARGO: FillValue = $-999.$ f ; float Ascat_{-10-prior-days-wind-at-ARGO(N-prof, N-DAYS-WIND);} Ascat 10 prior days wind at ARGO:long name = "Prior 10 days time series of Ascat wind speed module at Argo float location" : Ascat_10_prior_days_wind_at_ARGO:units = \degree m/s \degree ; $\text{Ascat}_10_\text{prior}_d$ at ARGO_F illValue = -999.f; float CMORPH_{-10-prior-days-Rain-Rate-at-ARGO(N-prof, N-3H-RAIN);} $CMORPH_10$ -prior days Rain Rate at ARGO:long name $=$ "Prior 10 days times series of 3hourly CMORPH Rain Rate at Argo float location" ; CMORPH 10 prior days Rain Rate at ARGO:units = "mm/3h" ; $CMORPH_10_1$ prior days Rain Rate at ARGO: FillValue = -999.1 ; float SSS_ISAS_at_ARGO(N_prof); SSS ISAS at ARGO:long name = "ISAS SSS (5m depth) at Argo float location" ; $SSS₁SAS_{at}ARGO:units = "1"$; SSS ISAS at ARGO:salinity scale = "Practical Salinity Scale(PSS-78)" ; SSS ISAS at ARGO:standard name = "sea water salinity" ; SSS_ISAS_at_ARGO:_FillValue = -999.f; float SSS_PCTVAR_ISAS_at_ARGO(N_prof); SSS PCTVAR ISAS at ARGO:long name = "Error on ISAS SSS (5m depth) at Argo float loca-

tion $(\%$ variance)" ; $SSS_PCTVAR \, ISAS \, \text{at} \, ARGO: units = "%" ;$ SSS PCTVAR ISAS at ARGO: FillValue = -999.f ; float SSS_WOA13_at_ARGO(N_prof); SSS WOA13 at ARGO:long name = "WOA 2013 (DECAV-1deg) SSS (0m depth) at Argo float location" ; $SSS₁WOA13_{at}ARGO:units = "1"$; SSS WOA13 at ARGO:salinity scale = "Practical Salinity Scale(PSS-78)" ; SSS WOA13 at ARGO:standard name = "sea surface salinity" ; $SSS_WOA13_at_ARGO: FillValue = -999.f;$ float SSS_STD_WOA13_at_ARGO(N_prof); SSS STD WOA13 at ARGO:long name = "WOA 2013 (DECAV-1deg) SSS STD (0m depth) at Argo float location " ; $SSS_STD_WOA13_at_ARGO:units = "1"$; SSS_STD WOA13_at_ARGO:_FillValue = -999.f : // global attributes: :Conventions $=$ "CF-1.6" ; :title = "ARGO Match-Up Database" ; :Satellite_product_name = "SMOS L3 CATDS CECOS LOCEAN V2.1 9DAYS 25KM"; :Satellite_product_spatial_resolution = $"25 \text{ km"}$; :Satellite_product_temporal_resolution $=$ "9 days" ; :Satellite_product_filename = "v2.1/9days/SMOS_L3_DEBIAS_LOCEAN_AD_20100116_EASE_09d_25km_v00.nc" ; : Match-Up_spatial_window_radius_in_km = $25.$; :Match-Up_temporal_window_radius_in_days $= 2$.; :start_time = "20100114T000005Z" ; :stop time = "20100118T235026Z" ; :northernmost latitude = 77.676f ; :sourthenmost latitude $= -66.423f$; :westernmost_longitude $= -179.219f$: :easternmost_longitude $= 179.199f$; :geospatial lat -units $=$ "degrees north" ; :geospatial lat resolution $=$ "25 km" ; :geospatial_lon_units $=$ "degrees east" ; :geospatial_lon_resolution = $"25 \text{ km" }$; :institution = "ESA-IFREMER-ODL" ; :project name = "SMOS Pilote Mission Exploitation Platfrom (Pi-MEP) for salinity" ; :project url = "https://pimep-project.odl.bzh" ; :license $=$ "Pi-MEP data use is free and open" ; :product_version $= "1.0"$; : keywords = "Oceans > Ocean Salinity > Sea Surface Salinity" ; :acknowledgment = "Please acknowledge the use of these data with the following statement: These data were provided by SMOS Pilote Mission Exploitation Platfrom (Pi-MEP) for salinity" ; :source = "v2.1/9days/SMOS_L3_DEBIAS_LOCEAN_AD_20100116_EASE_09d_25km_v00.nc"; :references = "https://pimep-project.odl.bzh" ; :history = "Processed on 2018-04-18 using MDB generator" ; :date_created = $"2018-04-18$ 17:09:30";

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}

2.5 MDB characteristics for the particular in situ/satellite pairs

2.5.1 Number of paired SSS data as a function of time and distance to coast

Figure 1: Number of match-ups between Argo and SMOS-L3-CATDS-CECOS-LOCEAN-V3- 18DAYS-25KM SSS as a function of time (a) and as function of the distance to coast (b) over the South Atlantic Ocean Pi-MEP region and for the full satellite product period.

2.5.2 Histograms of the SSS match-ups

Figure 2: Histograms of SSS from Argo (a) and SMOS-L3-CATDS-CECOS-LOCEAN-V3- 18DAYS-25KM (b) considering all match-up pairs per bins of 0.1 over the South Atlantic Ocean Pi-MEP region and for the full satellite product period.

2.5.3 Distribution in situ SSS depth in match-ups pairs

Figure 3: Histograms of the depth of the upper level SSS measurements from Argo in the Match-up DataBase for the South Atlantic Ocean Pi-MEP region (a) and temporal mean spatial distribution of pressure of the in situ SSS data over 1◦x1◦ boxes and for the full satellite product period (b).

2.5.4 Spatial Distribution of Match-ups

Figure 4: Number of SSS match-ups between Argo SSS and the SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM SSS product for the South Atlantic Ocean Pi-MEP region over 1 ◦x1◦ boxes and for the full satellite product period.

2.5.5 Histograms of the spatial and temporal lags of the match-ups pairs

Figure 5: Histograms of the spatial (a) and temporal (b) lags between the time of the Argo measurements and the date of the corresponding SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM SSS product.

3 MDB file Analyses

3.1 Spatial Maps of the Temporal mean and STD of in situ and satellite SSS and of the difference (∆SSS)

In Figure [6,](#page-18-1) we show maps of temporal mean (left) and standard deviation (right) of the SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM satellite SSS product (top) and of the Argo in situ dataset at the collected Pi-MEP match-up pairs. The temporal mean and std are gridded over the full satellite product period and over spatial boxes of size $1°x1°$.

At the bottom of Figure [6,](#page-18-1) the temporal mean (left) and standard deviation (right) of the differences between the satellite SSS product and in situ data found at match-up pairs, namely ∆SSS(Satellite -Argo), is also gridded over the full satellite product period and over spatial boxes of size 1◦x1◦ .

Figure 6: Temporal mean (left) and STD (right) of SSS from SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM (top), Argo (middle), and of ∆SSS (Satellite - Argo). Only matchup pairs are used to generate these maps.

3.2 Time series of the monthly averaged mean and STD of in situ and satellite SSS and of the (∆SSS)

In the top panel of Figure [7,](#page-19-1) we show the time series of the monthly averaged SSS estimated over the full South Atlantic Ocean Pi-MEP region for both SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM satellite SSS product (in black) and the Argo in situ dataset (in blue) at the collected Pi-MEP match-up pairs.

In the middle panel of Figure [7,](#page-19-1) we show the time series of the monthly averaged Δ SSS (Satellite - Argo) for the collected Pi-MEP match-up pairs and estimated over the full South

Atlantic Ocean Pi-MEP region.

In the bottom panel of Figure [7,](#page-19-1) we show the time series of the monthly averaged standard deviation of the ∆SSS (Satellite - Argo) for the collected Pi-MEP match-up pairs and estimated over the full South Atlantic Ocean Pi-MEP region.

Figure 7: Time series of the monthly averaged mean SSS (top), mean ∆SSS (Satellite - Argo) and STD of ∆SSS (Satellite - Argo) over the South Atlantic Ocean Pi-MEP region considering all match-ups collected by the Pi-MEP platform.

3.3 Zonally-averaged Time-mean and temporal STD of in situ and satellite SSS and of the ∆SSS

In Figure [8](#page-20-0) left panel, we show the zonally averaged time-mean SSS estimated at the collected Pi-MEP match-up pairs for both SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM satellite SSS product (in black) and the Argo in situ dataset (in blue). The time mean is evaluated over the full satellite SSS product period.

In the right panel of Figure [8,](#page-20-0) we show the zonally averaged time-mean Δ SSS (Satellite - Argo) for all the collected Pi-MEP match-up pairs estimated over the full satellite product period.

LOCEAN-V3-18DAYS-25KM (black) and from Argo (blue). Right panel: zonally averaged time-mean ∆SSS (Satellite - Argo) for all the collected Pi-MEP match-up pairs estimated over the full satellite product period.

3.4 Scatterplots of satellite vs in situ SSS by latitudinal bands

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Figure 9: Contour maps of the concentration of SMOS-L3-CATDS-CECOS-LOCEAN-V3- 18DAYS-25KM SSS (y-axis) versus Argo SSS (x-axis) at match-up pairs for different latitude bands. For each plot, the red line shows $x=y$. The black thin and dashed lines indicate a linear fit through the data cloud and the $\pm 95\%$ confidence levels, respectively. The number match-up pairs n, the slope and R^2 coefficient of the linear fit, the root mean square (RMS) and the mean bias between satellite and in situ data are indicated for each latitude band in each plots.

3.5 Time series of the monthly averaged mean and STD of the ∆SSS sorted by latitudinal bands

Figure 10: Monthly-average mean (red curves) ∆SSS (Satellite - Argo) and ±1 STD (black vertical thick bars) as function of time for all the collected Pi-MEP match-up pairs estimated over the South Atlantic Ocean Pi-MEP region and for the full satellite product period are shown for different latitude bands: (a) Latitude band 80◦S-80◦N, (b) latitude band 20◦S-20◦N, (c) Mid Latitude bands 40◦S-20◦S and 20◦N-40◦N and (d) Latitude bands 60◦S-40◦S and 40◦N-60◦N.

3.6 ∆SSS sorted as function of geophysical conditions

In Figure [11,](#page-23-0) we classify the match-up differences ∆SSS (Satellite - in situ) between SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM and Argo SSS as function of the geophysical conditions at match-up points. The mean and std of ∆SSS (Satellite - Argo) is thus evaluated as function of the

- in situ SSS values per bins of width 0.2,
- in situ SST values per bins of width 1◦C,
- ASCAT daily wind values per bins of width 1 m/s ,
- CMORPH 3-hourly rain rates per bins of width 1 mm/h, and,
- distance to coasts per bins of width 50 km.

(e) Distance to coast

Figure 11: ∆SSS (Satellite - Argo) sorted as function of Argo SSS values a), Argo SST b), ASCAT Wind speed c), CMORPH rain rate d) and distance to coast (e). In all plots the mean and STD of Δ SSS for each bin is indicated by the red curves and black vertical thick bars (± 1) STD)

In Figures [12](#page-24-0) and [13,](#page-25-1) we focus on sub-datasets of the match-up differences ∆SSS (Satellite - in situ) between SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM and Argo for the following specific geophysical conditions:

- C1:if the local value at in situ location of estimated rain rate is high (ie. $> 10 \text{ mm/h}$) and mean daily wind is low (ie. $< 5 \text{ m/s}$).
- C2: if the prior 10-days history of the rain and wind at in situ location show high (ie. > 5 mm/h) and low (ie. $< 5 m/s$) median values, respectively.
- C3:if both C1 and C2 are met.

- C4:if the mixed layer is shallow with depth <20 m.
- C5:if there is a barrier layer with thickness > 10 m.
- C6:if the in situ data is located where the climatological sss standard deviation is high (ie. above > 0.2).

For each of these conditions, the temporal mean (gridded over spatial boxes of size $1°x1°$) and the histogram of the difference ∆SSS (Satellite - in situ) are presented.

(d) $\text{MLD} < 20\text{m}$ (e) $\text{BLT} > 10\text{m}$ (f) Locations where WOA2013 SSS STD > 0.2 Figure 12: Temporal mean gridded over spatial boxes of size 1◦x1◦ of ∆SSS (SMOS-L3- CATDS-CECOS-LOCEAN-V3-18DAYS-25KM - Argo) for 6 different subdatasets corresponding to:RR>1mm/h and U_{10} <5m/s (a), RR^{10d} >5mm/h and U_{10}^{10d} <5m/s (b), C1 U C2 (c) ,MLD<20m (d),BLT>10m (e),Locations where WOA2013 SSS STD>0.2 (f).

Figure 13: Normalized histogram of ∆SSS (SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM - Argo) for 6 different subdatasets corresponding to: $RR>1mm/h$ and U_{10} <5m/s (a), $\text{RR}^{10d} > 5\text{mm/h}$ and $U_{10}^{10d} < 5\text{m/s}$ (b), C1 U C2 (c),MLD<20m (d),BLT>10m (e),Locations where WOA2013 SSS STD>0.2 (f).

4 Summary

Table 1 presents statistics (mean, median, standard deviation, root mean square and interquantile range) of the match-up differences ∆SSS (Satellite - in situ) between SMOS-L3-CATDS-CECOS-LOCEAN-V3-18DAYS-25KM and Argo derived over the South Atlantic Ocean Pi-MEP region and for the full satellite product period and for the following conditions:

- all: All the match-up pairs satellite/in situ SSS are used to derive the statistics
- C1: only pairs where RR>1mm/h and U_{10} <5m/s
- C2: only pairs where $\text{RR}^{10d} > 5 \text{mm/h}$ and $U_{10}^{10d} < 5 \text{m/s}$
- C3: only pairs where C1 U C2
- C4: only pairs where MLD<20m
- C5: only pairs where BLT>10m
- C6: only pairs at Locations where WOA2013 SSS STD>0.2
- C7a: only pairs where distance to coast is < 150 km.
- C7b: only pairs where distance to coast is in the range [150, 800] km.
- C7c: only pairs where distance to coast is > 800 km.
- C8a: only pairs where in situ SST is $< 5^{\circ}$ C.
- C8b: only pairs where in situ SST is in the range [5, 28]◦C.
- C8c: only pairs where in situ SST is $> 28^{\circ}$ C.

- C9a: only pairs where in situ SSS is < 33.
- C9b: only pairs where in situ SSS is in the range [33, 37].
- C9c: only pairs where in situ SSS is > 37 .

Table 2 presents statistics of ∆SSS (Satellite - Argo) as Table 1 but for Argo delayed mode only.

Table 2: Statistics of ∆SSS (Satellite - Argo) - Delayed mode

For the same conditions, Table 3 presents statistics of ∆SSS (Satellite - ISAS). Only ISAS SSS values with PCTVAR<80% are used to derive the statistics.

Table 3: Statistics of \triangle SSS (Satellite - ISAS)							
Condition	#	Median	Mean	Std	RMS	IQR	
all	60275	0.02	0.01	$0.22\,$	0.22	0.22	
C1	187	NaN	-0.04	0.29	0.29	0.23	
$\rm C2$	379	$\rm NaN$	0.01	0.19	0.19	0.23	
C ₃	0	NaN	NaN	NaN	Na	NaN	
C ₄	8603	NaN	-0.03	0.37	0.37	0.27	
C5	15115	NaN	0.01	0.19	0.19	0.22	
C6	4139	NaN	-0.05	0.38	0.38	0.30	
C7a	1508	NaN	-0.12	0.45	0.46	0.28	
C7b	31051	NaN	-0.00	0.23	0.23	0.22	
$\rm C7c$	27716	NaN	0.03	0.17	0.17	0.21	
C8a	2358	NaN	0.11	0.18	0.21	0.23	
C8b	55552	NaN	0.01	0.20	0.20	0.21	
$\rm C8c$	2362	NaN	-0.11	0.47	0.48	0.28	
C9a	132	-0.61	-0.82	1.16	1.42	1.07	
C9b	57197	NaN	0.01	0.21	0.21	0.22	
C9c	2946	-0.00	-0.01	0.16	0.16	0.20	

Table 3: Statistics of ∆SSS (Satellite - ISAS)

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- Argo. Argo float data and metadata from global data assembly centre (argo gdac), 2000. [doi:](http://dx.doi.org/10.17882/42182) [10.17882/42182.](http://dx.doi.org/10.17882/42182)
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