Match-up database Analyses Report

SMAP SSS L3 v5.0 - Monthly (JPL)

TSG (Lauge-Koch)

Arctic Ocean

prepared by the Pi-MEP Consortium

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Acronym

Aquarius	NASA/CONAE Salinity mission
ASCAT	Advanced Scatterometer
ATBD	Algorithm Theoretical Baseline Document
BLT	Barrier Layer Thickness
CMORPH	CPC MORPHing technique (precipitation analyses)
CPC	Climate Prediction Center
CTD	Instrument used to measure the conductivity, temperature, and pressure of seawater
DM	Delayed Mode
EO	Earth Observation
ESA	European Space Agency
FTP	File Transfer Protocol
GOSUD	Global Ocean Surface Underway Data
GTMBA	The Global Tropical Moored Buoy Array
Ifremer	Institut français de recherche pour l'exploitation de la mer
IPEV	Institut polaire français Paul-Émile Victor
IQR	Interquartile range
ISAS	*In Situ* Analysis System
Kurt	Kurtosis (fourth central moment divided by fourth power of the standard deviation)
L2	Level 2
LEGOS	Laboratoire d'Etudes en Géophysique et Océanographie Spatiales
LOCEAN	Laboratoire d'Océanographie et du Climat : Expérimentations et Approches Numériques
LOPS	Laboratoire d'Océanographie Physique et Spatiale
MDB	Match-up Data Base
MEOP	Marine Mammals Exploring the Oceans Pole to Pole
MLD	Mixed Layer Depth
NCEI	National Centers for Environmental Information
NRT	Near Real Time
NTAS	Northwest Tropical Atlantic Station
OI	Optimal interpolation
Pi-MEP	Pilot-Mission Exploitation Platform
PIRATA	Prediction and Researched Moored Array in the Atlantic
QC	Quality control
R_{sat}	Spatial resolution of the satellite SSS product
RAMA	Research Moored Array for African-Asian-Australian Monsoon Analysis and Prediction
r^2	Square of the Pearson correlation coefficient
RMS	Root mean square
RR	Rain rate
SAMOS	Shipboard Automated Meteorological and Oceanographic System
Skew	Skewness (third central moment divided by the cube of the standard deviation)
SMAP	Soil Moisture Active Passive (NASA mission)
SMOS	Soil Moisture and Ocean Salinity (ESA mission)
SPURS	Salinity Processes in the Upper Ocean Regional Study
SSS	Sea Surface Salinity
SSS_{insitu}	*In situ* SSS data considered for the match-up

SSS_{SAT}	Satellite SSS product considered for the match-up
ΔSSS	Difference between satellite and *in situ* SSS at colocalized point (ΔSSS = SSS_{SAT}- SSS_{insitu})
SST	Sea Surface Temperature
Std	Standard deviation
Std⋆	Robust Standard deviation = median(abs(x-median (x)))/0.67 (less affected by outliers than Std)
Stratus	Surface buoy located in the eastern tropical Pacific
Survostral	SURVeillance de l'Océan AuSTRAL (Monitoring the Southern Ocean)
TAO	Tropical Atmosphere Ocean
TSG	ThermoSalinoGraph
WHOI	Woods Hole Oceanographic Institution
WHOTS	WHOI Hawaii Ocean Time-series Station
WOA	World Ocean Atlas

1 Overview

In this report, we present systematic analyses of the Match-up DataBase (MDB) files generated by the Pi-MEP platform within the following Pi-MEP region and for the below pair of Satellite/*in situ* SSS data:

- Pi-MEP region: Arctic Ocean (download the corresponding mask in NetCDF here)
- SSS satellite product (SSS_{SAT}): SMAP SSS L3 v5.0 - Monthly (JPL)
- *In situ* dataset (SSS_{Insitu}): TSG (Lauge-Koch) (download the corresponding *in situ* report here)

In the following, ΔSSS= SSS_{SAT}- SSS_{Insitu} denotes the difference between the satellite and *in situ* SSS at the colocalized points that form the MDB.

This report presents successively:

The MDB file DataSets (Section 2)

- A short description of the satellite SSS product considered in the match-up (2.1)
- A short description of the *in situ* SSS dataset considered in the match-up (2.2)
- A short description of the auxiliary geophysical datasets co-localized with SSS pairs (2.3)
- An overview of how the Match-ups were evaluated (2.4)
- An overview of the MDB characteristics for the particular *in situ*/satellite pairs (2.5)

The major results of the MDB file Analyses (Section 3)

- Spatial Maps of the Time-mean and temporal Std of *in situ* and satellite SSS and of the ΔSSS (3.1)
- Time series of the monthly median and Std of *in situ* and satellite SSS and of the ΔSSS (3.2)
- Zonal mean and Std of *in situ* and satellite SSS and of the ΔSSS (3.3)
- Scatterplots of satellite vs *in situ* SSS by latitudinal bands (3.4)
- Time series of the monthly median and Std of the ΔSSS sorted by latitudinal bands (3.5)
- ΔSSS sorted as function of geophysical parameters (3.6)
- ΔSSS maps and statistics for different geophysical conditions (3.7)

All analyses are conducted over the Pi-MEP Region specified above and over the full satellite SSS product period. Original figures appearing in this report can be downloaded as PNG files here or by clicking directly on the figure.

2 The MDB file datasets

2.1 Satellite SSS product

2.1.1 SMAP SSS L3 v5.0 - Monthly (JPL)

This is the PI-produced JPL SMAP-SSS V5.0 CAP, level 3, monthly mapped sea surface salinity (SSS) product from the NASA Soil Moisture Active Passive (SMAP) observatory. It is based on the Combined Active-Passive (CAP) retrieval algorithm developed at JPL originally in the context of Aquarius/SAC-D and now extended to SMAP. JPL SMAP V5.0 SSS is based on the newly released SMAP V5 Level-1 Brightness Temperatures (TB). An enhanced calibration methodology has been applied to the brightness temperatures, which improves absolute radiometric calibration and reduces the biases between ascending and descending passes. The improved SMAP TB Level 1 TB will enhance the use of SMAP Level-1 data for other applications, such as sea surface salinity and winds. L3 monthly product file variables include: derived SSS with associated uncertainties and wind speed from SMAP and ancillary surface salinity from HYCOM. SMAP data begins on April 1, 2015 and is ongoing, with a 1 month latency in processing and availability. L3 products are global in extent and gridded at 0.25° x 0.25° with an approximate spatial resolution of 60 km. The SMAP satellite is in a near-polar orbit at an inclination of 98 degrees and an altitude of 685 km. It has an ascending node time of 6 pm and is sun-synchronous. With its 1000 km swath, SMAP achieves global coverage in approximately 3 days, but has an exact orbit repeat cycle of 8 days. On board instruments include a highly sensitive L-band radiometer operating at 1.41 GHz and an L-band 1.26 GHz radar sensor providing complementary active and passive sensing capabilities. Malfunction of the SMAP scatterometer on 7 July for the surface roughness correction required for the surface salinity retrieval.

Table 1: Satellite SSS product characteristics

SMAP SSS L3 v5.0 - Monthly (JPL)	
Spatial resolution	~60 km gridded at 0.25° x 0.25°
Temporal resolution	1 Month
Temporal coverage	From 2015-04-01 to now
Spatial coverage	Global [-180 180 -90 90]
Data Provider	JPL Climate Oceans and Solid Earth group
Release Date	2020-12-11
Version	5.0
User Guide	SMAP-SSS_JPL_V5.0_Documentation.pdf
Documentation	JPL-CAP_V50
DOI	http://doi.org/10.5067/SMP50-3TMCS
Link	SMAP_JPL_L3_SSS_CAP_MONTHLY_V50

2.2 *In situ* SSS dataset

The TSG (Lauge-Koch) dataset features underway ThermoSalinoGraph salinity measurements collected by Danish HDMS LAUGE KOCH military ship. This dataset spans the summer months of 2018 to 2020.

2.3 Auxiliary geophysical datasets

Additional EO datasets are used to characterize the geophysical conditions at the *in situ*/satellite SSS pair measurement locations and time, and 10 days prior to the measurements, to get an estimate of the geophysical concomitant condition and history. As discussed in Boutin et al. (2016), the presence of vertical gradients in, and horizontal variability of, sea surface salinity indeed complicates comparison of satellite and *in situ* measurements. The additional EO data are used here to get a first estimates of conditions for which L-band satellite SSS measured in the first centimeters of the upper ocean within a 50-150 km diameter footprint might differ from pointwise *in situ* measurements performed in general between 10 and 5 m depth below the surface. The spatio-temporal variability of SSS within a satellite footprint (50–150 km) is a major issue for satellite SSS validation in the vicinity of river plumes, frontal zones, and significant precipitation areas, among others. Rainfall can in some cases produce vertical salinity gradients exceeding 1 pss m^{-1}; consequently, it is recommended that satellite and *in situ* SSS measurements less than 3–6 h after rain events should be considered with care when used in satellite calibration/validation analyses. To identify such situation, the Pi-MEP platform is first using CMORPH products to characterize the local value and history of rain rate and ASCAT gridded data are used to characterize the local surface wind speed and history. For validation purpose, the ISAS monthly SSS *in situ* analysed fields at 5 m depth are collocated and compared with the satellite SSS products. The use of ISAS is motivated by the fact that it is used in the SMOS L2 official validation protocol in which systematic comparisons of SMOS L2 retrieved SSS with ISAS are done. In complement to ISAS, monthly std climatological fields from the World Ocean Atlas (WOA13) at the match-up pairs location and date are also used to have an a priori information of the local SSS variability.

2.3.1 CMORPH

Precipitation are estimated using the CMORPH 3-hourly products at 1/4° resolution (Joyce et al. (2004)). CMORPH (CPC MORPHing technique) produces global precipitation analyses at very high spatial and temporal resolution. This technique uses precipitation estimates that have been derived from low orbiter satellite microwave observations exclusively, and whose features are transported via spatial propagation information that is obtained entirely from geostationary satellite IR data. At present NOAA incorporate precipitation estimates derived from the passive microwaves aboard the DMSP 13, 14 and 15 (SSM/I), the NOAA-15, 16, 17 and 18 (AMSU-B), and AMSR-E and TMI aboard NASA's Aqua, TRMM and GPM spacecraft, respectively. These estimates are generated by algorithms of Ferraro (1997) for SSM/I, Ferraro et al. (2000) for AMSU-B and Kummerow et al. (2001) for TMI. Note that this technique is not a precipitation estimation algorithm but a means by which estimates from existing microwave rainfall algorithms can be combined. Therefore, this method is extremely flexible such that any precipitation estimates from any microwave satellite source can be incorporated.

With regard to spatial resolution, although the precipitation estimates are available on a grid with a spacing of 8 km (at the equator), the resolution of the individual satellite-derived estimates is coarser than that - more on the order of 12 x 15 km or so. The finer "resolution" is obtained via interpolation.

In effect, IR data are used as a means to transport the microwave-derived precipitation features during periods when microwave data are not available at a location. Propagation vector matrices are produced by computing spatial lag correlations on successive images of geostationary satellite IR which are then used to propagate the microwave derived precipitation estimates. This process governs the movement of the precipitation features only. At a given location, the shape and intensity of the precipitation features in the intervening half hour periods between microwave scans are determined by performing a time-weighting interpolation between microwave-derived features that have been propagated forward in time from the previous microwave observation and those that have been propagated backward in time from the following microwave scan. NOAA refer to this latter step as "morphing" of the features.

For the present Pi-MEP products, we only considered the 3-hourly products at 1/4 degree resolution. The entire CMORPH record (December 2002-present) for 3-hourly, 1/4 degree lat/lon resolution can be found at: ftp://ftp.cpc.ncep.noaa.gov/precip/CMORPH_V1.0/CRT/. CMORPH estimates cover a global belt (-180°W to 180°E) extending from 60°S to 60°N latitude and are available for the complete period of the Pi-MEP core datasets (Jan 2010-now).

2.3.2 ASCAT

Advanced SCATterometer (ASCAT) daily data produced and made available at Ifremer/CERSAT on a 0.25°x0.25° resolution grid (Bentamy and Fillon (2012)) since March 2007 are used to characterize the mean daily wind at the match-up pair location as well as the wind history during the 10-days period preceding the in situ measurement date. These wind fields are calculated based on a geostatistical method with external drift. Remotely sensed data from ASCAT are considered as observations while those from numerical model analysis (ECMWF) are associated with the external drift. The spatial and temporal structure functions for wind speed, zonal and meridional wind components are estimated from ASCAT retrievals. Furthermore, the new procedure includes a temporal interpolation of the retrievals based on the complex empirical orthogonal function (CEOF) approach, in order to enhance the sampling length of the scatterometer observations. The resulting daily wind fields involves the main known surface wind patterns as well as some variation modes associated with temporal and spatial moving features. The accuracy of the gridded winds was investigated through comparisons with moored buoy data in Bentamy et al. (2012) and resulted in rms differences for wind speed and direction are about 1.50 m.s^{-1} and 20°.

2.3.3 ISAS

The In Situ Analysis System (ISAS), as described in Gaillard et al. (2016) is a data based re-analysis of temperature and salinity fields over the global ocean 70°N–70°S on a 1/2° grid. It was initially designed to synthesize the temperature and salinity profiles collected by the Argo program. It has been later extended to accommodate all type of vertical profile as well as time series. ISAS gridded fields are entirely based on *in situ* measurements. The methodology and configuration have been conceived to preserve as much as possible the data information content and resolution. ISAS is developed and run in a research laboratory (LOPS) in close collaboration with Coriolis, one of Argo Global Data Assembly Center and unique data provider for the Mercator operational oceanography system. In Pi-MEP, the products used are the INSITU_GLO_PHY_TS_OA_MY_013_052 for the period 2010 to 2021 and the INSITU_GLO_PHY_TS_OA_NRT_013_002 for the Near-Real Time (2022-2023) derived at the Coriolis data center and provided by the Copernicus Marine Environment Monitoring Service (CMEMS). The major contribution to the data set is from Argo array of profiling floats, reaching an approximate resolution of one profile every 10-days and every 3-degrees over the satellite SSS period (http://www.umr-lops.fr/SNO-Argo/Products/ISAS-T-S-fields/). The ISAS optimal interpolation involves a structure function modeled as the sum of two Gaussian functions, each associated with specific time and space scales, resulting in a smoothing over typically 3 degrees. The smallest scale which can be retrieved with ISAS analysis is not smaller than 300–500 km (Kolodziejczyk et al. (2015)). For validation purpose, the ISAS monthly SSS fields at 5 m depth are collocated and compared with the satellite SSS products and included in the Pi-MEP

Match-up files. In addition, the "percentage of variance" fields (PCTVAR) contained in the ISAS analyses provide information on the local variability of *in situ* SSS measurements within 1/2°x1/2° boxes.

2.3.4 World Ocean Atlas Climatology

The World Ocean Atlas (WOA) is a set of objectively analyzed (1° grid) climatological fields of *in situ* temperature, salinity and other variables provided at standard depth levels for annual, seasonal, and monthly compositing periods for the World Ocean. It also includes associated statistical fields of observed oceanographic profile data interpolated to standard depth levels on 5°, 1°, and 0.25° grids. We use these fields in complement to ISAS to characterize the climatological fields (montly mean and std) at the match-up pairs location and date.

2.4 Overview of the Match-ups generation method

The match-up production is basically a three steps process:

1. preparation of the input *in situ* and satellite data, and,
2. co-localization of satellite products with *in situ* SSS measurements.
3. co-localization of the *in situ*/satellite pair with auxiliary information.

In the following, we successively detail the approaches taken for these different steps.

2.4.1 *In situ*/Satellite data filtering

The first step consists in filtering TSG (Lauge-Koch) *in situ* data using the quality flags as described in 2.2 so that only valid salinity data remain in the final match-up files.

For high-spatial resolution *in situ* SSS measurements such as the Thermo-SalinoGraph (TSG) SSS data, as well as SSS data from surface drifters, an additional spatial filtering step is performed on the *in situ* data that will be eventually compared to the satellite SSS products. If R_{sat} is the spatial resolution of the satellite SSS product (L2 to L3-L4), the *in situ* data are spatially low pass filtered using a running median filter with a window width=R_{sat} to try to minimize the spatial representation uncertainty when comparing to the lower spatial resolution of the satellite SSS product. Both original and filtered *in situ* data are finally stored in the MDB files.

Only for satellite L2 SSS data, a third sub-step consists in filtering spurious data using the flags and associated recommendations as provided by the official data centers and described in 2.1.

2.4.2 *In situ*/Satellite Co-localization

In this step, each SSS satellite product is co-localized with the filtered *in situ* measurements. The method used for co-location is different if the satellite SSS is a swath product (so-called Level 2-types) or a time-space composite product (so-called Level 3/level 4-types).

- For L2 SSS swath data :

  If R_{sat} is the spatial resolution of the satellite swath SSS product, for each *in situ* data sample collected in the Pi-MEP database, the platform searches for all satellite SSS data found at grid nodes located within a radius of $R_{sat}/2$ from the *in situ* data location and acquired with a time-lag from the *in situ* measurement date that is less or equal than ± 12 hours. If several satellite SSS samples are found to meet these criteria, the final satellite

SSS match-up point is selected to be the closest in time from the *in situ* data measurement date. The final spatial and temporal lags between the *in situ* and satellite data are stored in the MDB files.

- For L3 and L4 composite SSS products :

  If R_{sat} is the spatial resolution of the composite satellite SSS product and D the period over which the composite product was built (e.g., periods of 1, 7, 8, 9, 10, 18 days, 1 month, etc..) with central time t_o, then for each *in situ* data sample in the Pi-MEP database within the time interval $[t_o - D/2, t_o + D/2]$, the platform searches for all satellite SSS data of the composite product found at grid nodes located within a radius of $R_{sat}/2$ from the *in situ* data location. If several satellite SSS product samples are found to meet these criteria, the final satellite SSS match-up point is chosen to be the composite SSS with central time t_o which is the closest in time to the *in situ* data measurement date. The final spatial and temporal lags between the *in situ* and satellite data are stored in the MDB file.

Recently, in the context of the partnership with NASA, the Pi-MEP provides a new co-localization criterion that is applied only to L2 products, called "L2-Averaged". It consists in averaging all SSS L2 swath pixels falling in a spatio-temporal window defined by R_{sat}=50km and $D = \pm 3.5$ days around the in situ location. The spatial and temporal lags stored in the MDB files correspond to the average of all lags for each in situ data.

2.4.3 MDB pair Co-localization with auxiliary data and complementary information

MDB data consist of satellite and *in situ* SSS pairs but also of auxiliary geophysical parameters such as local and history of wind speed and rain rates, as well as various information (climatology, distance to coast, mixed layer depth, barrier layer thickness, etc) that can be derived from *in situ* data and which are included in the final match-up files. The collocation of auxiliary parameters and additional information is done for each *in situ* SSS measurement contained in the match-up files as follows :

If t_{insitu} is the time/date at which the *in situ* measurement is performed, we collect:

- The ASCAT wind speed product of the same day than t_{insitu} found at the ASCAT 1/4° grid node with closest distance from the *in situ* data location. We then store the time series of the ASCAT wind speed at the same node for the 10 days prior to the *in situ* measurement day.

- If the *in situ* data is located within the 60°N-60°S band, we select the CMORPH 3-hourly product that is closest in time from t_{insitu} and found at the CMORPH 1/4° grid node with closest distance from the *in situ* data location. We then store the time series of the CMORPH rain rate at the same node for the 10 days prior to the *in situ* measurement time.

For the given month/year of the *in situ* data, we select the ISAS and WOA fields for the same month (and same year for ISAS fields) and take the SSS analysis (monthly mean, std) found at the closest grid node from the *in situ* measurement.

The distance from the *in situ* SSS data location to the nearest coast is evaluated and provided in km. We use a distance-to-coast map at 1/4° resolution where small islands have been removed.

When vertical profiles of salinity (S) and temperature (T) are made available from the *in situ* measurements used to build the match-up (Argo or marine mammals), the following variables are also included into each satellite/*in situ* match-up file:

1. The vertical distribution of pressure at which the profiles were measured,
2. The vertical S(z) and T(z) profiles,
3. The vertical potential density anomaly profile $\sigma_0(z)$,
4. The Mixed Layer Depth (MLD). The MLD is defined here as the depth where the potential density has increased from the reference depth (10 meter) by a threshold equivalent to 0.2°C decrease in temperature at constant salinity: $\sigma_0 = \sigma_{010m} + \Delta\sigma_0$ with $\Delta\sigma_0 = \sigma_0(\theta_{10m} - 0.2, S_{10m}) - \sigma_0(\theta_{10m}, S_{10m})$ where θ_{10m} and S_{10m} are the temperature and salinity at the reference depth (i.e. 10 m) (de Boyer Montégut et al. (2004), de Boyer Montégut et al. (2007)).
5. The Top of the Thermocline Depth (TTD) is defined as the depth at which temperature decreases from its 10 m value by 0.2°C.
6. The Barrier Layer thickness (BLT) is defined as the difference between the MLD and the TTD. If BLT<0, it corresponds to a vertically density compensated layer whose thickness is then the absolute value of (TTD-MLD).
7. The vertical profile of the buoyancy frequency $N^2(z)$

The resulting match-ups files are serialized as NetCDF-4 files whose structure depends on the origin of the *in situ* data and is described in section 2.4.4.

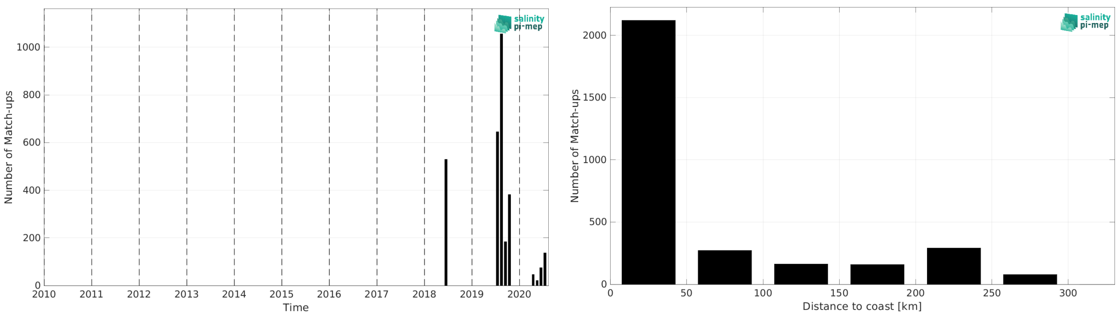
2.4.4 Content of the Match-Up NetCDF files

The content of the Match-Up NetCDF files for TSG (Lauge-Koch) is described here.

2.5 MDB characteristics for each specific *in situ*/satellite pair

2.5.1 Number of paired SSS data as a function of time and distance to coast

Figure 2 shows the time (a) and distance to coast (b) distributions of the match-ups between TSG (Lauge-Koch) and SMAP SSS L3 v5.0 - Monthly (JPL) for the Arctic Ocean Pi-MEP region and for the full satellite product period.

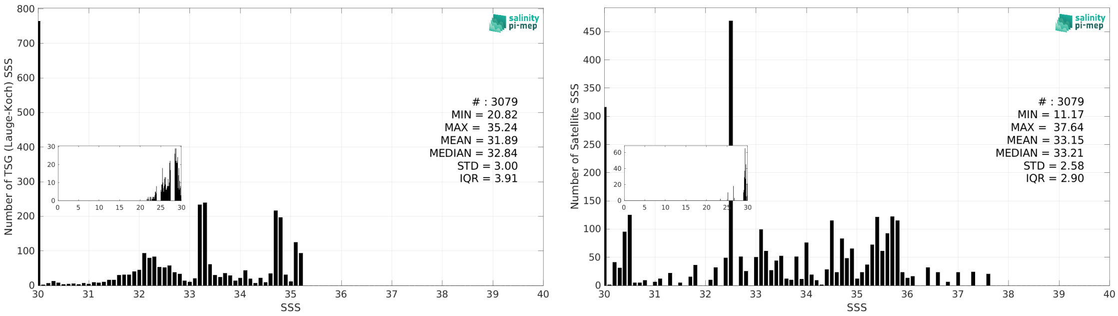


(a) (b)

Figure 2: Number of match-ups between TSG (Lauge-Koch) and SMAP SSS L3 v5.0 - Monthly (JPL) SSS as a function of time (a) and as function of the distance to coast (b) over the Arctic Ocean Pi-MEP region and for the full satellite product period.

2.5.2 Histograms of the SSS match-ups

Figure 3 shows the SSS distribution of TSG (Lauge-Koch) (a) and SMAP SSS L3 v5.0 - Monthly (JPL) (b) considering all match-up pairs per bins of 0.1 over the Arctic Ocean Pi-MEP region and for the full satellite product period.

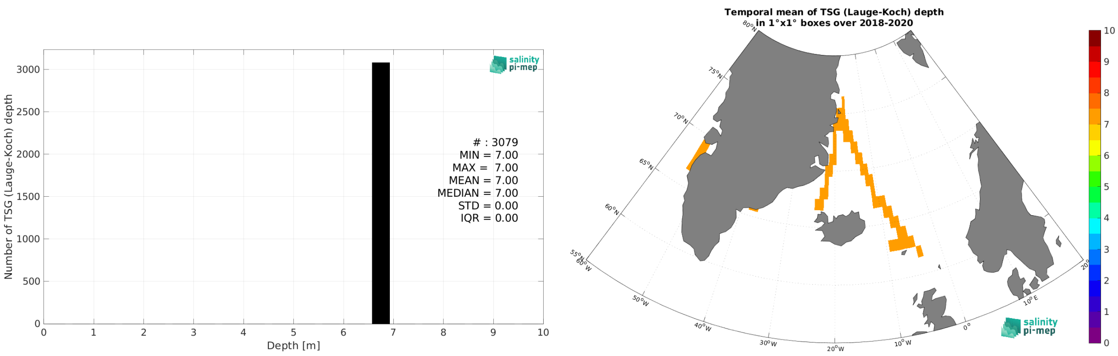


(a) (b)

Figure 3: Histograms of SSS from TSG (Lauge-Koch) (a) and SMAP SSS L3 v5.0 - Monthly (JPL) (b) considering all match-up pairs per bins of 0.1 over the Arctic Ocean Pi-MEP region and for the full satellite product period.

2.5.3 Distribution of *in situ* SSS depth measurements

Figure 4 shows the depth distribution of the upper level SSS measurements from TSG (Lauge-Koch) in the Match-up DataBase for the Arctic Ocean Pi-MEP region (a) and temporal mean spatial distribution of pressure of the *in situ* SSS data over 1°×1° boxes and for the full satellite product period (b).



(a) (b)

Figure 4: Histograms of the depth of the upper level SSS measurements from TSG (Lauge-Koch) in the Match-up DataBase for the Arctic Ocean Pi-MEP region (a) and temporal mean spatial distribution of pressure of the *in situ* SSS data over 1°×1° boxes and for the full satellite product period (b).

2.5.4 Spatial Distribution of Match-ups

The number of SSS match-ups between TSG (Lauge-Koch) SSS and the SMAP SSS L3 v5.0 - Monthly (JPL) SSS product for the Arctic Ocean Pi-MEP region over 1°×1° boxes and for the full satellite product period is shown in Figure 5.

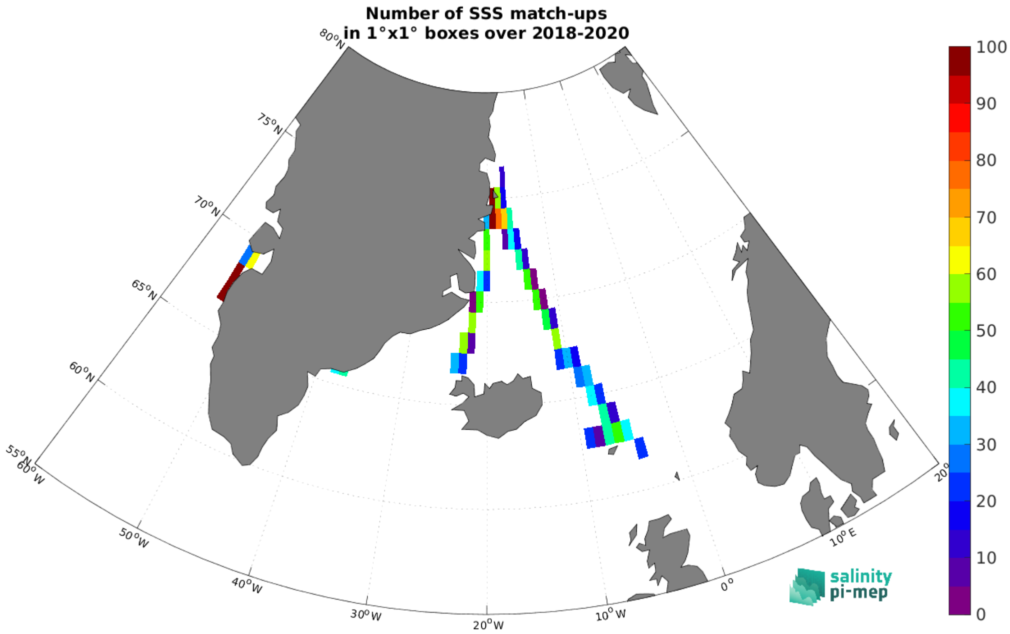
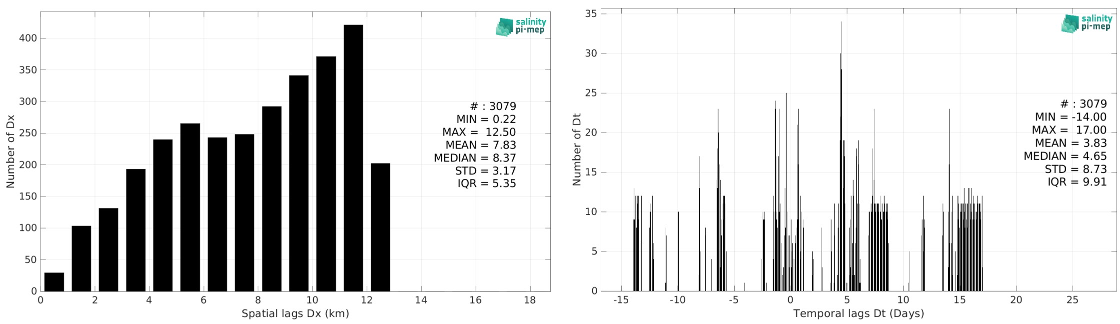


Figure 5: Number of SSS match-ups between TSG (Lauge-Koch) SSS and the SMAP SSS L3 v5.0 - Monthly (JPL) SSS product for the Arctic Ocean Pi-MEP region over 1°×1° boxes and for the full satellite product period.

2.5.5 Histograms of the spatial and temporal lags of the match-ups pairs

Figure 6 reveals the spatial (left) and temporal (right) lags between the location/time of the TSG (Lauge-Koch) measurement and the position/date of the corresponding SMAP SSS L3 v5.0 - Monthly (JPL) SSS pixel of all match-ups pairs.



(a) (b)

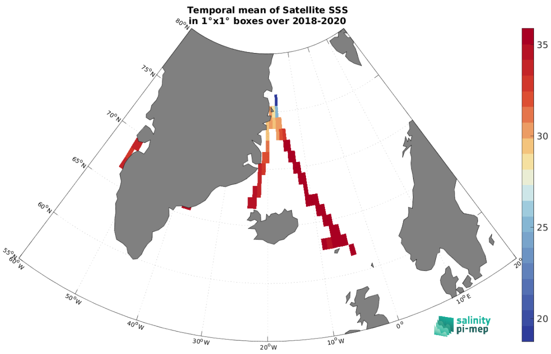
Figure 6: Histograms of the spatial (a) and temporal (b) lags between the location/time of the TSG (Lauge-Koch) measurement and the date of the corresponding SMAP SSS L3 v5.0 - Monthly (JPL) SSS pixel.

3 MDB file Analyses

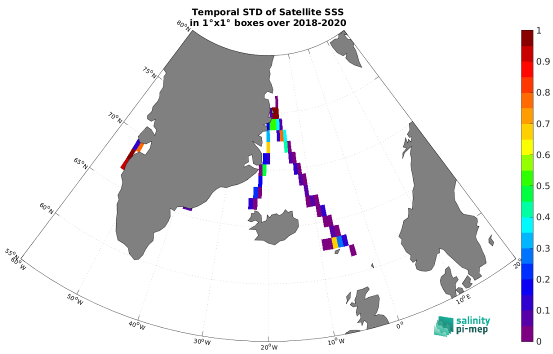
3.1 Spatial Maps of the Temporal mean and Std of *in situ* and satellite SSS and of their difference (ΔSSS)

In Figure 7, we show maps of temporal mean (left) and standard deviation (right) of the SMAP SSS L3 v5.0 - Monthly (JPL) (top) and of the TSG (Lauge-Koch) *in situ* dataset at the collected Pi-MEP match-up pairs. The temporal mean and std are gridded over the full satellite product period and over spatial boxes of size $1° \times 1°$.

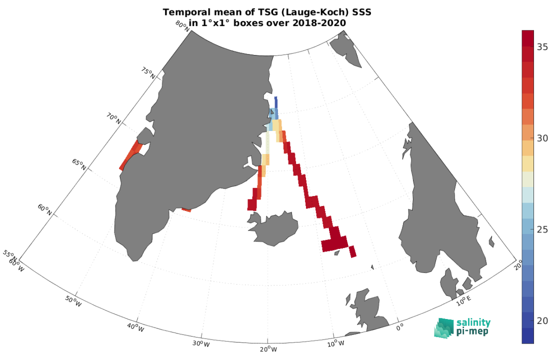
At the bottom of Figure 7, the temporal mean (left) and standard deviation (right) of the differences between the satellite SSS product and *in situ* data found at match-up pairs, namely ΔSSS(Satellite -TSG (Lauge-Koch)), is also gridded over the full satellite product period and over spatial boxes of size $1° \times 1°$.



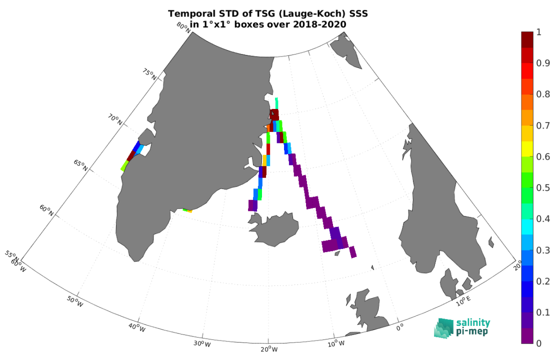
(a) MEAN(Satellite SSS)



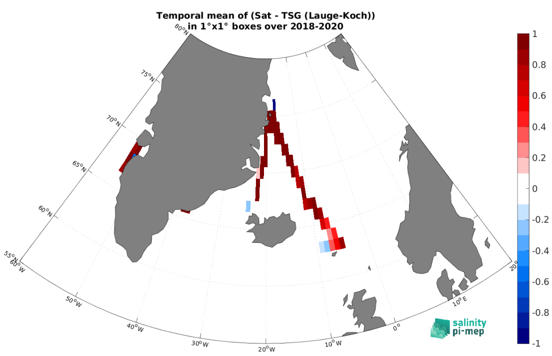
(b) Std(Satellite SSS)



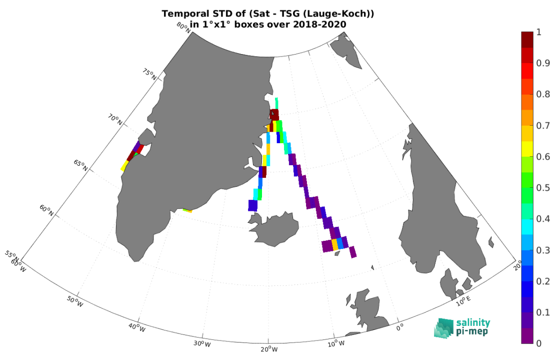
(c) MEAN(TSG (Lauge-Koch) SSS)



(d) Std(TSG (Lauge-Koch) SSS)



(e) MEAN(ΔSSS) (Satellite - TSG (Lauge-Koch))



(f) Std(ΔSSS) (Satellite - TSG (Lauge-Koch))

Figure 7: Temporal mean (left) and Std (right) of SSS from SMAP SSS L3 v5.0 - Monthly (JPL) (top), TSG (Lauge-Koch) (middle), and of ΔSSS (Satellite - TSG (Lauge-Koch)). Only match-up pairs are used to generate these maps.

3.2 Time series of the monthly median and Std of *in situ* and satellite SSS and of their difference (ΔSSS)

In the top panel of Figure 8, we show the time series of the monthly median SSS estimated over the full Arctic Ocean Pi-MEP region for both SMAP SSS L3 v5.0 - Monthly (JPL) satellite SSS product (in black) and the TSG (Lauge-Koch) *in situ* dataset (in blue) at the collected Pi-MEP match-up pairs.

In the middle panel of Figure 8, we show the time series of the monthly median of ΔSSS (Satellite - TSG (Lauge-Koch)) for the collected Pi-MEP match-up pairs and estimated over the full Arctic Ocean Pi-MEP region.

In the bottom panel of Figure 8, we show the time series of the monthly standard deviation of ΔSSS (Satellite - TSG (Lauge-Koch)) for the collected Pi-MEP match-up pairs and estimated over the full Arctic Ocean Pi-MEP region.

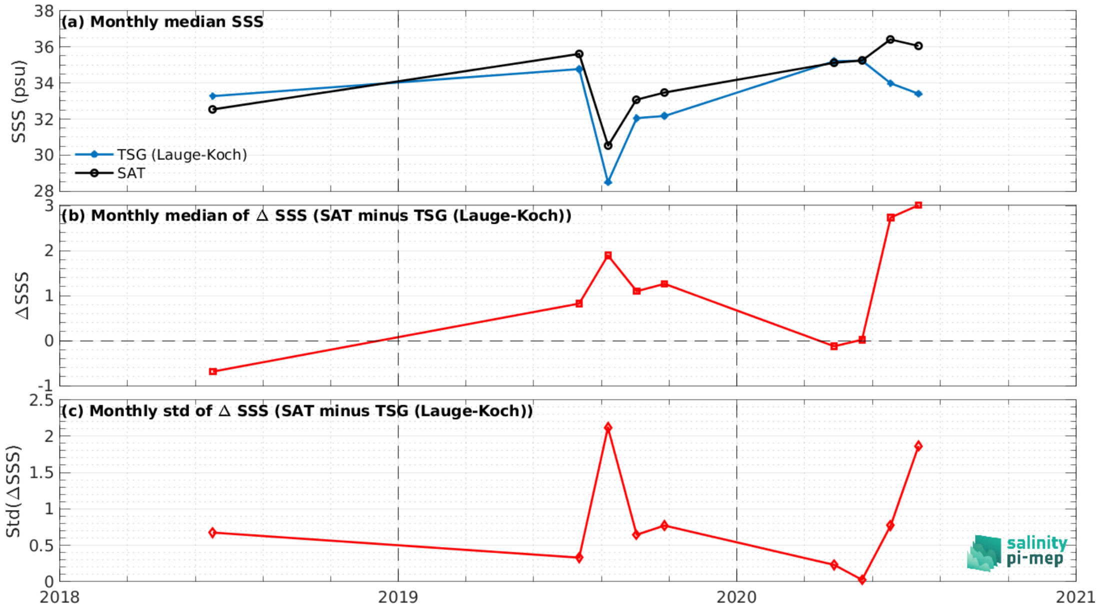


Figure 8: Time series of the monthly median SSS (top), median of ΔSSS (Satellite - TSG (Lauge-Koch)) and Std of ΔSSS (Satellite - TSG (Lauge-Koch)) over the Arctic Ocean Pi-MEP region considering all match-ups collected by the Pi-MEP.

3.3 Zonal mean and Std of *in situ* and satellite SSS and of the difference (ΔSSS)

In Figure 9 left panel, we show the zonal mean SSS considering all Pi-MEP match-up pairs for both SMAP SSS L3 v5.0 - Monthly (JPL) satellite SSS product (in black) and the TSG (Lauge-Koch) *in situ* dataset (in blue). The full satellite SSS product period is used to derive the mean.

In the right panel of Figure 9, we show the zonal mean of ΔSSS (Satellite - TSG (Lauge-Koch)) for all the collected Pi-MEP match-up pairs estimated over the full satellite product period.

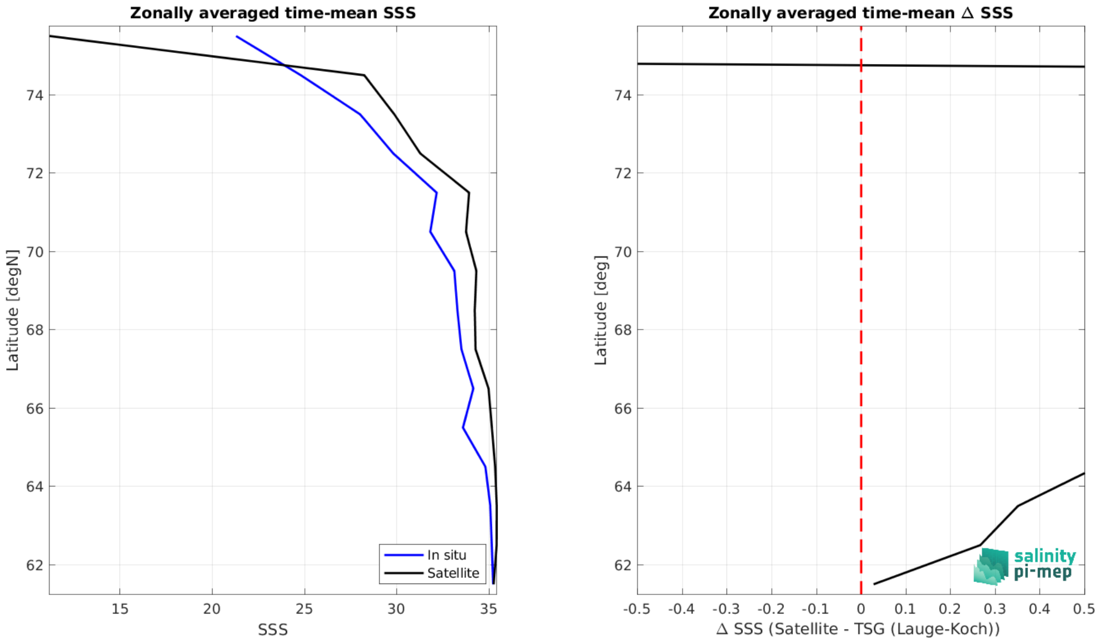
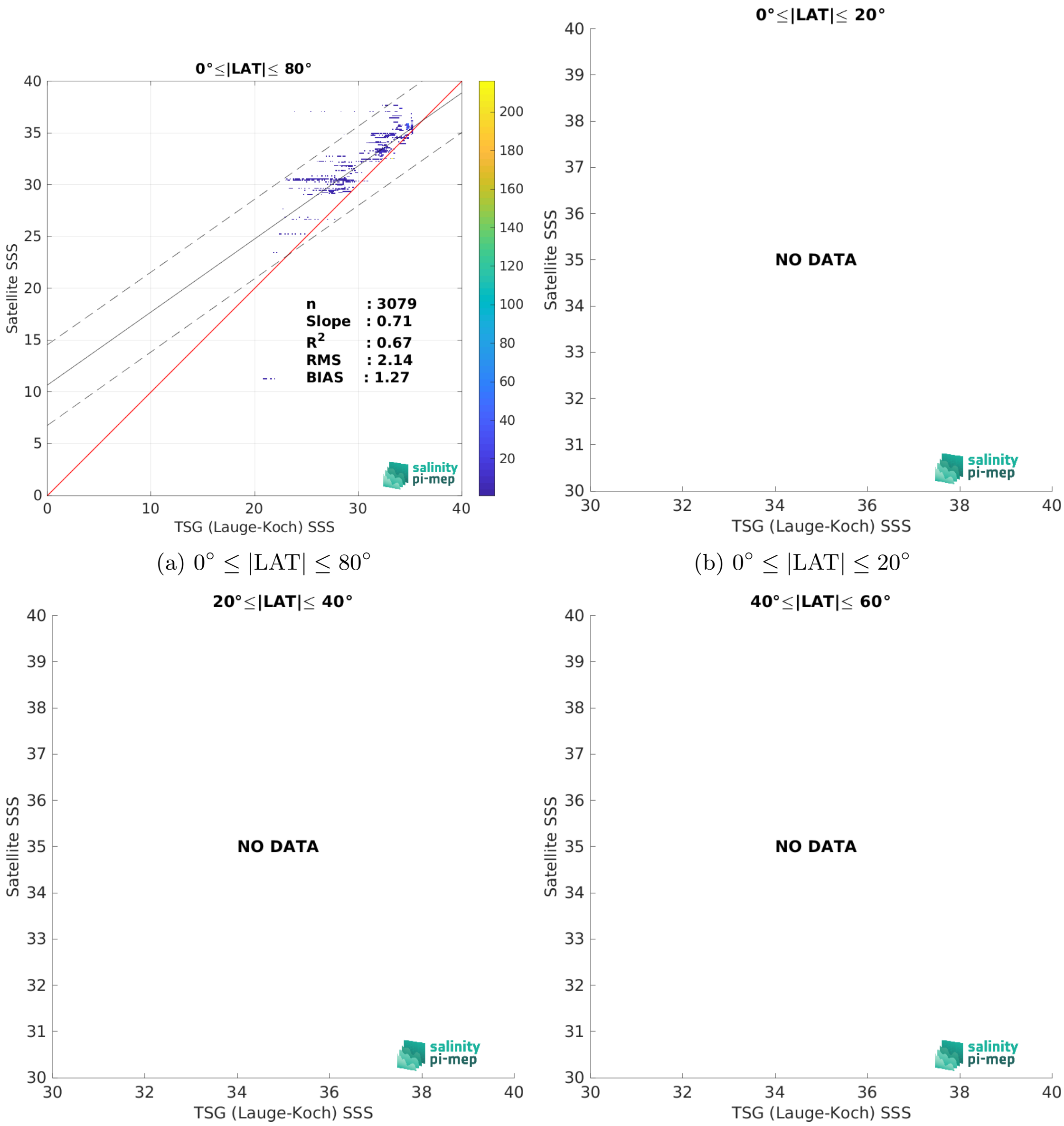


Figure 9: Left panel: Zonal mean SSS from SMAP SSS L3 v5.0 - Monthly (JPL) satellite product (black) and from TSG (Lauge-Koch) (blue). Right panel: Zonal mean of ΔSSS (Satellite - TSG (Lauge-Koch)) for all the collected Pi-MEP match-up pairs estimated over the full satellite product period.

3.4 Scatterplots of satellite vs *in situ* SSS by latitudinal bands

In Figure 10, contour maps of the concentration of SMAP SSS L3 v5.0 - Monthly (JPL) SSS (y-axis) versus TSG (Lauge-Koch) SSS (x-axis) at match-up pairs for different latitude bands: (a) 80°S-80°N, (b) 20°S-20°N, (c) 40°S-20°S and 20°N-40°N and (d) 60°S-40°S and 40°N-60°N. For each plot, the red line shows x=y. The black thin and dashed lines indicate a linear fit through the data cloud and the ±95% confidence levels, respectively. The number match-up pairs n, the slope and R^2 coefficient of the linear fit, the root mean square (RMS) and the mean bias between satellite and *in situ* data are indicated for each latitude band in each plots.



(a) 0° ≤ |LAT| ≤ 80°

(b) 0° ≤ |LAT| ≤ 20°

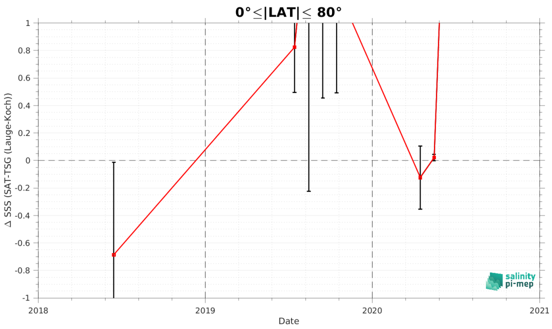
(c) 20° ≤ |LAT| ≤ 40°

(d) 40° ≤ |LAT| ≤ 60°

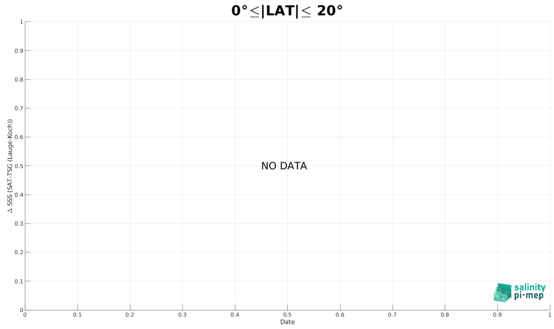
Figure 10: Contour maps of the concentration of SMAP SSS L3 v5.0 - Monthly (JPL) SSS (y-axis) versus TSG (Lauge-Koch) SSS (x-axis) at match-up pairs for different latitude bands. For each plot, the red line shows x=y. The black thin and dashed lines indicate a linear fit through the data cloud and the ±95% confidence levels, respectively. The number match-up pairs n, the slope and R^2 coefficient of the linear fit, the root mean square (RMS) and the mean bias between satellite and *in situ* data are indicated for each latitude band in each plots.

3.5 Time series of the monthly median and Std of ΔSSS sorted by latitudinal bands

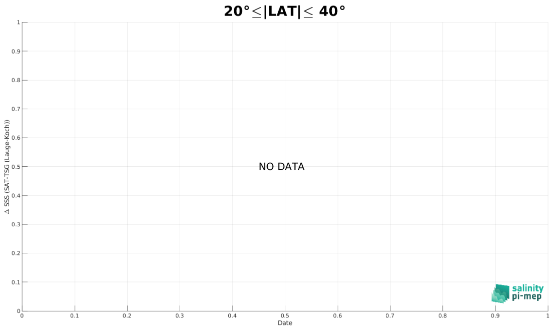
In Figure 11, time series of the monthly median (red curves) of ΔSSS (Satellite - TSG (Lauge-Koch)) and ±1 Std (black vertical thick bars) as function of time for all the collected Pi-MEP match-up pairs estimated over the Arctic Ocean Pi-MEP region and for the full satellite product period are shown for different latitude bands: (a) 80°S-80°N, (b) 20°S-20°N, (c) 40°S-20°S and 20°N-40°N and (d) 60°S-40°S and 40°N-60°N.



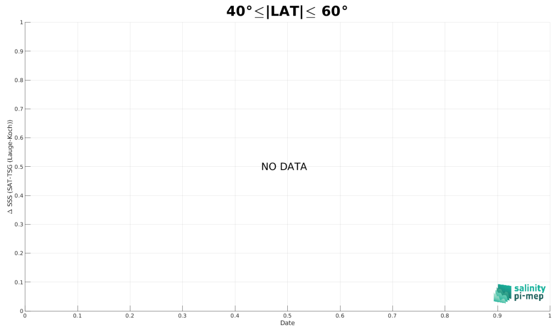
(a) $0° \leq |\text{LAT}| \leq 80°$



(b) $0° \leq |\text{LAT}| \leq 20°$



(c) $20° \leq |\text{LAT}| \leq 40°$



(d) $40° \leq |\text{LAT}| \leq 60°$

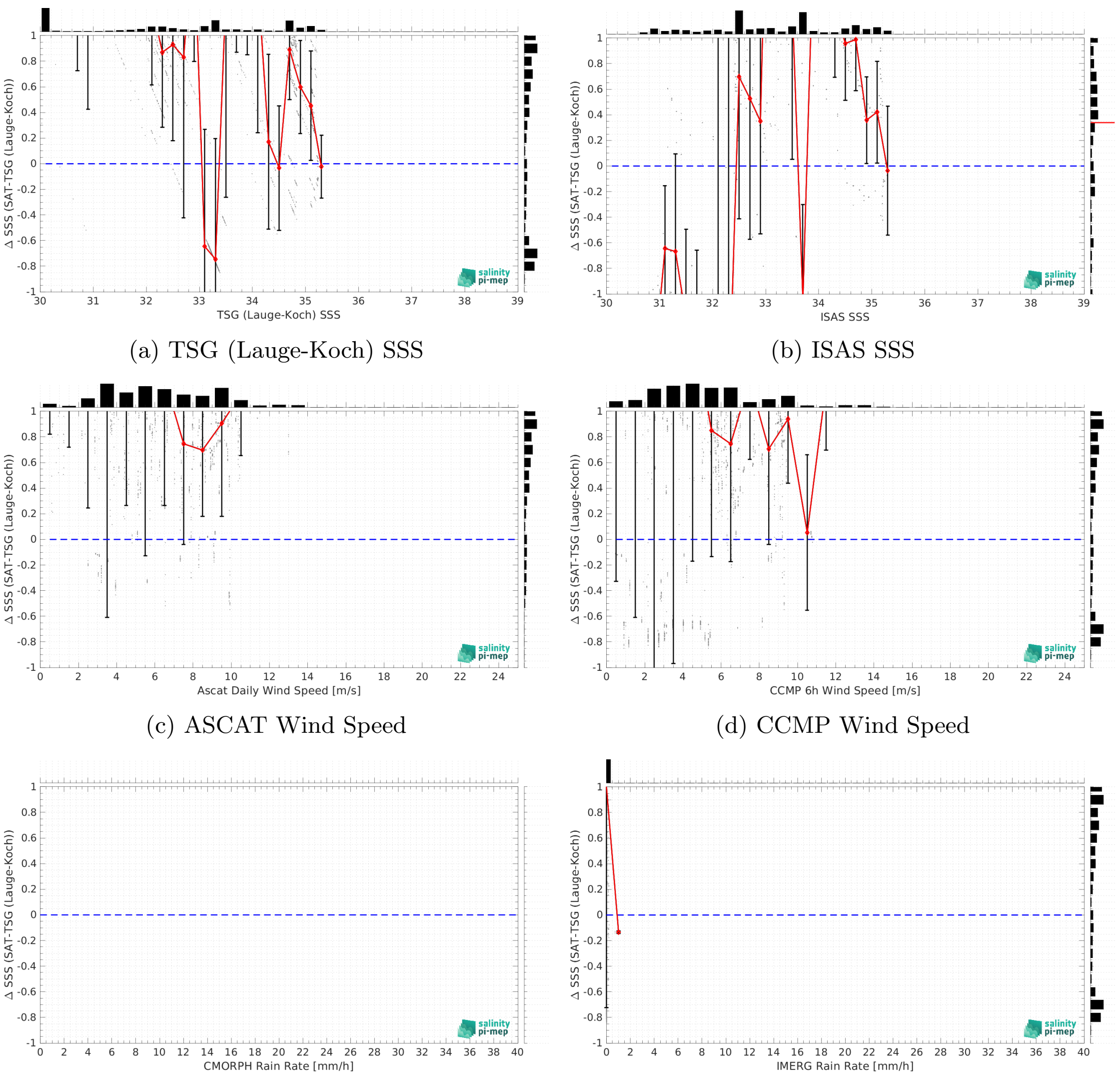
Figure 11: Monthly median (red curves) of ΔSSS (Satellite - TSG (Lauge-Koch)) and ±1 Std (black vertical thick bars) as function of time for all the collected Pi-MEP match-up pairs estimated over the Arctic Ocean Pi-MEP region and for the full satellite product period are shown for different latitude bands: (a) 80°S-80°N, (b) 20°S-20°N, (c) 40°S-20°S and 20°N-40°N and (d) 60°S-40°S and 40°N-60°N.

3.6 ΔSSS sorted as function of geophysical parameters

In Figures 12 and 13, we classify the match-up differences ΔSSS (Satellite - *in situ*) between SMAP SSS L3 v5.0 - Monthly (JPL) and TSG (Lauge-Koch) SSS as function of the geophysical conditions at match-up points. The median and std of ΔSSS (Satellite - TSG (Lauge-Koch)) is thus evaluated as function of the

- *in situ* SSS values per bins of width 0.2,
- *in situ* SST values per bins of width 1°C,
- CCMP 6h/ASCAT daily wind values per bins of width 1 m/s,

- IMERG 30 min/CMORPH 3-hourly rain rates per bins of width 1 mm/h,
- distance to the coast per bins of width 50 km,
- distance to the ice edge per bins of width 50 km,
- *in situ* measurement depth (if relevant),
- sea ice fraction per bins of width 10%,
- CMC/ERA5/AVHRR SST values per bins of width 1°C,
- ISAS SSS values per bins of width 0.2.



(a) TSG (Lauge-Koch) SSS

(b) ISAS SSS

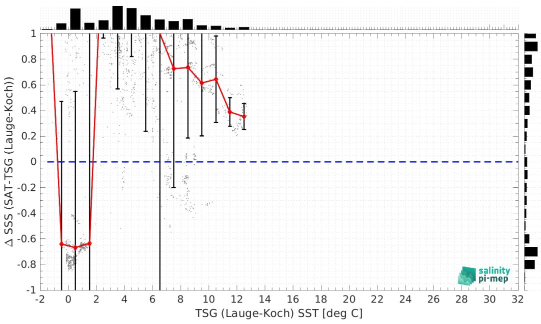
(c) ASCAT Wind Speed

(d) CCMP Wind Speed

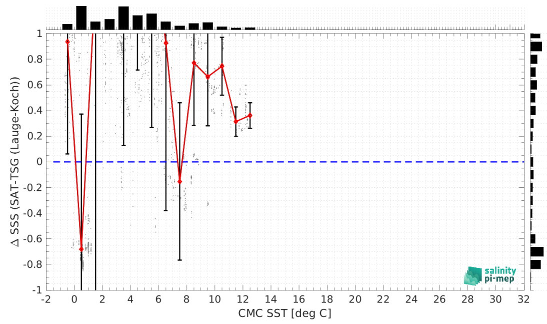
(e) CMORPH Rain rate

(f) IMERG Rain rate

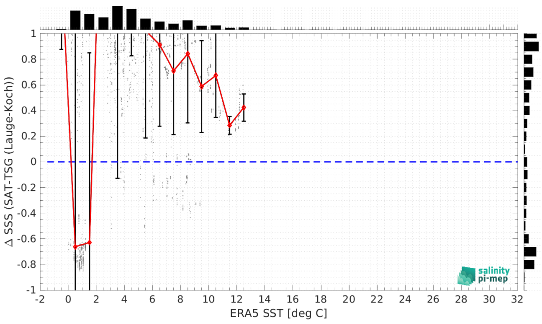
Figure 12: ΔSSS (Satellite - TSG (Lauge-Koch)) sorted as function of TSG (Lauge-Koch) SSS values (a), ISAS SSS (b), ASCAT Wind speed (c), CCMP Wind speed (d), CMORPH rain rate (e) and IMERG rain rate (f). In all plots the median and Std of ΔSSS for each bin is indicated by the red curves and black vertical thick bars (±1 Std).



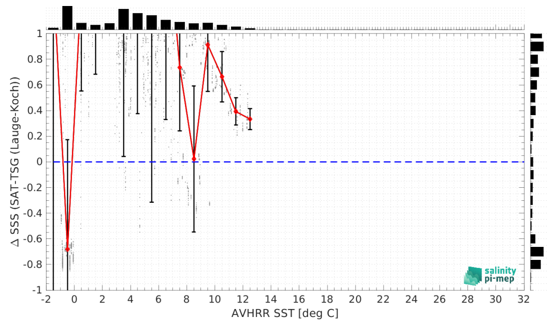
(a) TSG (Lauge-Koch) SST



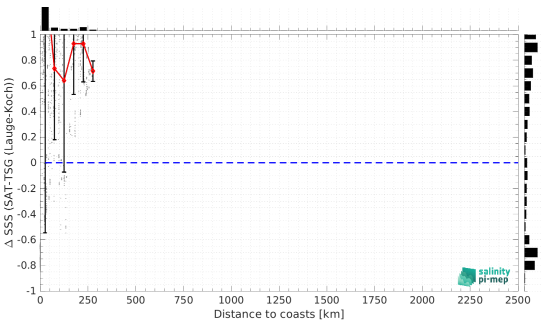
(b) CMC SST



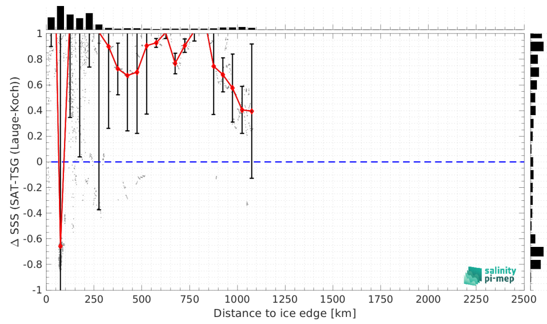
(c) ER5 SST



(d) AVHRR SST



(e) Distance to coast



(f) Distance to ice edge

Figure 13: ΔSSS (Satellite - TSG (Lauge-Koch)) sorted as function of TSG (Lauge-Koch) SST values (a), CMC SST (b), ERA5 SST (c), AVHRR SST (d), distance to coast (e) and distance to ice edge (f). In all plots the median and Std of ΔSSS for each bin is indicated by the red curves and black vertical thick bars (±1 Std). Links to similar figures sorted as function of Sea ice fraction and *in situ* measurement depth.

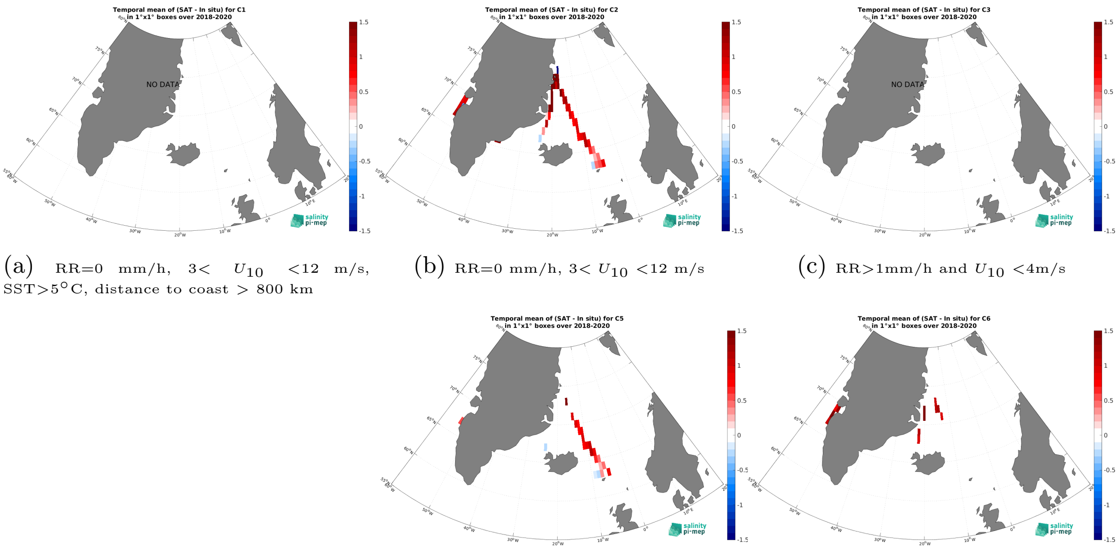
3.7 ΔSSS maps and statistics for different geophysical conditions

In Figures 14 and 15, we focus on sub-datasets of the match-up differences ΔSSS (Satellite - *in situ*) between SMAP SSS L3 v5.0 - Monthly (JPL) and TSG (Lauge-Koch) for the following specific geophysical conditions:

- **C1**:if the local value at *in situ* location of estimated rain rate is zero, mean daily wind is in the range [3, 12] m/s, the SST is > 5°C and distance to coast is > 800 km.

- **C2**:if the local value at *in situ* location of estimated rain rate is zero, mean daily wind is in the range [3, 12] m/s.
- **C3**:if the local value at *in situ* location of estimated rain rate is high (ie. > 1 mm/h) and mean daily wind is low (ie. < 4 m/s).
- **C5**:if the *in situ* data is located where the climatological SSS standard deviation is low (ie. above < 0.2).
- **C6**:if the *in situ* data is located where the climatological SSS standard deviation is high (ie. above > 0.2).

For each of these conditions, the temporal mean (gridded over spatial boxes of size 1°×1°) and the histogram of the difference ΔSSS (Satellite - *in situ*) are presented.



(a) RR=0 mm/h, 3< U_{10} <12 m/s, SST>5°C, distance to coast > 800 km

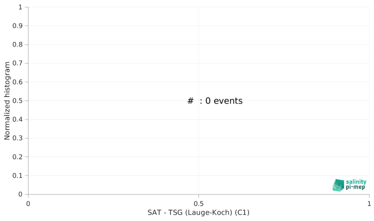
(b) RR=0 mm/h, 3< U_{10} <12 m/s

(c) RR>1mm/h and U_{10} <4m/s

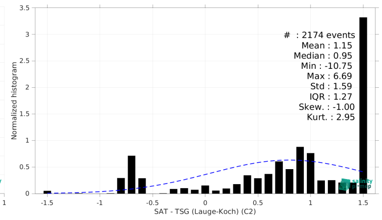
(d) WOA2013 SSS Std<0.2

(e) WOA2013 SSS Std>0.2

Figure 14: Temporal mean gridded over spatial boxes of size 1°×1° of ΔSSS (SMAP SSS L3 v5.0 - Monthly (JPL) - TSG (Lauge-Koch)) for 5 different subdatasets corresponding to:RR=0 mm/h, 3< U_{10} <12 m/s, SST>5°C, distance to coast > 800 km (a), RR=0 mm/h, 3< U_{10} <12 m/s (b), RR>1mm/h and U_{10} <4m/s (c), WOA2013 SSS Std<0.2 (d), WOA2013 SSS Std>0.2 (e).

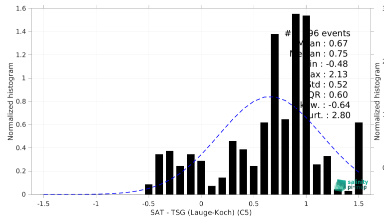


(a) RR=0 mm/h, 3< U_{10} <12 m/s, SST>5°C, distance to coast > 800 km

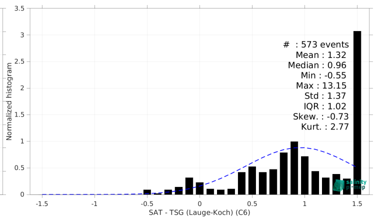


(b) RR=0 mm/h, 3< U_{10} <12 m/s

(c) RR>1mm/h and U_{10} <4m/s



(d) WOA2013 SSS Std<0.2



(e) WOA2013 SSS Std>0.2

Figure 15: Normalized histogram of ΔSSS (SMAP SSS L3 v5.0 - Monthly (JPL) - TSG (Lauge-Koch)) for 5 different subdatasets corresponding to: RR=0 mm/h, 3< U_{10} <12 m/s, SST>5°C, distance to coast > 800 km (a), RR=0 mm/h, 3< U_{10} <12 m/s (b), RR>1mm/h and U_{10} <4m/s (c), WOA2013 SSS Std<0.2 (d), WOA2013 SSS Std>0.2 (e).

4 Summary

► Table 1 shows the mean, median, standard deviation (Std), root mean square (RMS), interquartile range (IQR), correlation coefficient (r^2) and robust standard deviation (Std*) of the match-up differences ΔSSS (Satellite - *in situ*) between SMAP SSS L3 v5.0 - Monthly (JPL) and TSG (Lauge-Koch) derived over the Arctic Ocean Pi-MEP region and for the full satellite product period and for the following conditions:

- all: All the match-up pairs satellite/*in situ* SSS values are used to derive the statistics
- C1: only pairs where RR=0 mm/h, 3< U_{10} <12 m/s, SST>5°C, distance to coast > 800 km
- C2: only pairs where RR=0 mm/h, 3< U_{10} <12 m/s
- C3: only pairs where RR>1mm/h and U_{10} <4m/s
- C5: only pairs where WOA2013 SSS Std<0.2
- C6: only pairs at WOA2013 SSS Std>0.2
- C7a: only pairs with a distance to coast < 150 km.
- C7b: only pairs with a distance to coast in the range [150, 800] km.
- C7c: only pairs with a distance to coast > 800 km.
- C8a: only pairs where SST is < 5°C.
- C8b: only pairs where SST is in the range [5, 15]°C.

- C8c: only pairs where SST is > 15°C.
- C9a: only pairs where SSS is < 33.
- C9b: only pairs where SSS is in the range [33, 37].
- C9c: only pairs where SSS is > 37.

Table 1: Statistics of ΔSSS (Satellite - TSG (Lauge-Koch))

Condition	#	Median	Mean	Std	RMS	IQR	r^2	Std*
all	3079	1.00	1.27	1.73	2.14	1.59	0.670	1.24
C1	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
C2	2174	0.95	1.15	1.59	1.96	1.27	0.734	0.94
C3	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
C5	696	0.75	0.67	0.52	0.85	0.60	0.754	0.38
C6	573	0.96	1.32	1.37	1.90	1.02	0.478	0.71
C7a	2552	1.22	1.34	1.88	2.31	2.26	0.615	1.68
C7b	527	0.90	0.88	0.32	0.94	0.31	0.876	0.22
C7c	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
C8a	1898	1.34	1.28	1.83	2.23	2.80	0.581	1.61
C8b	1181	0.89	1.25	1.54	1.98	0.72	0.826	0.54
C8c	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
C9a	1562	1.79	2.07	1.86	2.78	1.71	0.589	1.24
C9b	1517	0.54	0.44	1.07	1.16	1.64	0.503	1.15
C9c	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN

► Table 2 presents statistics of ΔSSS (Satellite - ISAS) using only ISAS SSS values with PCTVAR<80%.

Table 2: Statistics of ΔSSS (Satellite - ISAS)

Condition	#	Median	Mean	Std	RMS	IQR	r^2	Std*
all	194	0.57	0.56	0.29	0.63	0.41	0.755	0.29
C1	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
C2	194	0.57	0.56	0.29	0.63	0.41	0.755	0.29
C3	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
C5	177	0.62	0.58	0.29	0.64	0.40	0.253	0.30
C6	17	0.25	0.35	0.14	0.38	0.29	1.000	0.00
C7a	39	0.02	0.16	0.21	0.26	0.27	0.983	0.14
C7b	155	0.63	0.66	0.21	0.69	0.35	0.093	0.26
C7c	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
C8a	17	0.25	0.35	0.14	0.38	0.29	1.000	0.00
C8b	177	0.62	0.58	0.29	0.64	0.40	0.253	0.30
C8c	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
C9a	17	0.25	0.35	0.14	0.38	0.29	1.000	0.00
C9b	177	0.62	0.58	0.29	0.64	0.40	0.253	0.30
C9c	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN

► Numerical values can be downloaded as csv files for Table 1 and Table 2.

5 More Comparison/Validation Materials

5.1 Comparisons with other satellite products

► Table 1 shows the mean, median, standard deviation (Std), root mean square (RMS), interquartile range (IQR), correlation coefficient (r^2) and robust standard deviation (Std*) of the match-up differences ΔSSS (Satellite - TSG (Lauge-Koch)) between different satellite products and **TSG (Lauge-Koch)** derived over the Arctic Ocean Pi-MEP region considering all match-up pairs satellite/*in situ* SSS values to derive the statistics:

Table 1: Statistics of ΔSSS (Satellite - TSG (Lauge-Koch)) - All

Satellite products	#	Median	Mean	Std	RMS	IQR	r^2	Std*
smos-l2-v700	1056	-1.48	-3.33	5.32	6.28	3.55	0.623	2.27
smap-l2-rss-v6	2202	0.15	0.56	1.57	1.67	1.74	0.451	1.14
smap-l2-rss-v6-40km	1666	0.23	0.32	1.91	1.94	2.00	0.128	1.49
smap-l2-jpl-v5.0	7787	0.54	-1.12	6.89	6.98	3.77	0.390	2.69
smos-l3-catds-cpdc-v333-l2q	380	-0.38	0.14	1.55	1.55	1.62	0.223	1.42
smos-l3-catds-cpdc-v332-9d	520	0.48	0.53	0.75	0.92	0.53	0.920	0.42
smos-l3-catds-cpdc-v335-10d-25km	541	0.61	0.73	0.91	1.17	0.73	0.883	0.58
smos-l3-catds-cpdc-v335-1m-25km	556	0.52	0.82	0.80	1.15	0.89	0.945	0.38
smos-l3-catds-locean-v9-9d	2176	0.45	0.35	2.13	2.16	1.36	0.531	0.95
smos-l3-catds-locean-v9-18d	2176	0.18	0.34	1.40	1.44	0.99	0.706	0.66
smos-l3-bec-v2-9d	2992	0.35	1.38	2.57	2.92	2.10	0.194	0.99
smap-l3-rss-v6-8dr	1196	0.10	-0.53	3.16	3.21	0.49	0.646	0.35
smap-l3-rss-v6-1m	1383	0.16	0.34	0.78	0.85	0.64	0.911	0.38
smap-l3-jpl-v5.0-8dr	4138	0.81	0.19	3.94	3.94	2.23	0.404	1.71
smap-l3-jpl-v5.0-1m	3079	1.00	1.27	1.73	2.14	1.59	0.670	1.24
smos-l4-bec-v2-1d	3351	0.29	1.17	2.25	2.54	1.57	0.308	0.85
smos-l4-cmems-catds-lops-oi-v346-1w	1941	0.49	2.37	4.49	5.08	3.15	0.367	1.13
smos-l4-cmems-cnr-v1-1d	5181	0.06	1.87	3.97	4.39	3.30	0.466	0.98
smos-l4-cmems-cnr-v1-1m	5358	-0.04	1.85	3.92	4.34	3.13	0.505	0.50
cci-l4-esa-merged-oi-v4.41-7dr	873	0.10	0.44	0.96	1.06	0.54	0.844	0.35
cci-l4-esa-merged-oi-v4.41-30dr	724	0.04	0.28	0.86	0.90	0.40	0.877	0.25
smap-l4-esr-oi-v3-1d	10684	0.15	0.80	1.81	1.98	1.26	0.747	0.80
smap-l4-esr-oi-v3-1m	3365	0.03	0.61	1.85	1.94	1.52	0.696	1.04
smos-l3-catds-locean-arctic-v2-9d	1336	0.49	0.84	1.08	1.37	1.28	0.908	0.78
smos-l3-catds-locean-arctic-v2-18d	1334	0.36	0.82	1.10	1.37	1.36	0.916	0.67
smos-l3-bec-arctic-v4-9d	3925	-0.16	0.59	2.14	2.22	0.85	0.324	0.59
cci-l4-esa-polar-nh-merged-oi-v4.41-7dr	806	0.08	0.46	0.97	1.07	0.57	0.850	0.36
cci-l4-esa-polar-nh-merged-oi-v4.41-30dr	687	0.06	0.36	0.83	0.91	0.43	0.907	0.28
cci-l4-esa-merged-oi-v5.5-7dr	841	0.19	0.49	1.18	1.28	0.46	0.657	0.36
cci-l4-esa-merged-oi-v5.5-30dr	722	0.17	0.47	0.99	1.10	0.41	0.830	0.32

► Table 2 is similar to Table 1 but considering only match-up pairs where RR=0 mm/h, 3< U_{10} <12 m/s, SST>5°C, distance to coast > 800 km.

Table 2: Statistics of ΔSSS (Satellite - TSG (Lauge-Koch)) - C1

Satellite products	#	Median	Mean	Std	RMS	IQR	r^2	Std*
smos-l2-v700	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smap-l2-rss-v6	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smap-l2-rss-v6-40km	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smap-l2-jpl-v5.0	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l3-catds-cpdc-v333-l2q	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l3-catds-cpdc-v332-9d	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l3-catds-cpdc-v335-10d-25km	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l3-catds-cpdc-v335-1m-25km	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l3-catds-locean-v9-9d	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l3-catds-locean-v9-18d	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l3-bec-v2-9d	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smap-l3-rss-v6-8dr	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smap-l3-rss-v6-1m	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smap-l3-jpl-v5.0-8dr	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smap-l3-jpl-v5.0-1m	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l4-bec-v2-1d	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l4-cmems-catds-lops-oi-v346-1w	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l4-cmems-cnr-v1-1d	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l4-cmems-cnr-v1-1m	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
cci-l4-esa-merged-oi-v4.41-7dr	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
cci-l4-esa-merged-oi-v4.41-30dr	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smap-l4-esr-oi-v3-1d	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smap-l4-esr-oi-v3-1m	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l3-catds-locean-arctic-v2-9d	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l3-catds-locean-arctic-v2-18d	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
smos-l3-bec-arctic-v4-9d	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
cci-l4-esa-polar-nh-merged-oi-v4.41-7dr	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
cci-l4-esa-polar-nh-merged-oi-v4.41-30dr	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
cci-l4-esa-merged-oi-v5.5-7dr	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
cci-l4-esa-merged-oi-v5.5-30dr	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN

▶ Numerical values can be downloaded as csv files for Table 1 and Table 2.

▶ Figures using numerical values of Table 1 sorted by MEDIANS, MEANS, IQR, RMS, STD, R2 are also provided.

▶ Figures using numerical values of Table 2 sorted by MEDIANS, MEANS, IQR, RMS, STD, R2 are also provided.

Caution has to be made in the interpretation of the "ranking" between different satellite products in particular when looking at the dispersion parameters like the standard deviation (STD), or the interquartile range (IQR). Keep in mind that low spatial and/or temporal resolution satellite SSS products tend to have lower dispersions than products at higher resolutions. For example, a level 2 (swath) product of a specific sensor will always have more dispersion than level 3 or 4 products where spatial and temporal averaging tend to reduce the instrumental noise and potential small scale variability. In general, products at 1°×1° spatial resolution have lower dispersion than products at 0.25°x0.25°. Same result applies for monthly products compared to daily products.

5.2 Statistics derived for the different *in situ* databases

▶ Table 1 shows the mean, median, standard deviation (Std), root mean square (RMS), interquartile range (IQR), correlation coefficient (r^2) and robust standard deviation (Std*) of the match-up differences ΔSSS (Satellite - *in situ*) between **SMAP SSS L3 v5.0 - Monthly (JPL)** and all the available *in situ* datasets derived over the Arctic Ocean Pi-MEP region and for the full satellite product period and considering all match-up pairs satellite/*in situ* SSS values to derive the statistics:

Table 1: Statistics of ΔSSS (Satellite - *in situ*)

***in situ* database**	**#**	**Median**	**Mean**	**Std**	**RMS**	**IQR**	**r^2**	**Std***
argo	20586	0.39	-0.12	2.80	2.80	0.79	0.311	0.57
tsg-legos-dm	60915	0.49	0.14	2.92	2.93	1.00	0.117	0.75
tsg-gosud-research-vessel	10830	0.43	0.47	0.53	0.71	0.65	0.687	0.50
tsg-gosud-sailing-ship	886	1.80	3.84	5.34	6.57	6.93	0.000	2.00
tsg-samos	4051	0.47	0.99	2.44	2.64	2.11	0.006	1.60
drifter	306	1.10	1.01	0.55	1.15	0.74	0.314	0.52
tsg-polarstern	75949	-1.58	-7.85	11.35	13.80	15.82	0.188	3.48
saildrone	105664	0.50	0.54	2.86	2.91	1.05	0.138	0.78
ices	56891	0.31	0.05	2.50	2.50	0.76	0.220	0.57
tsg-amundsen	170650	1.17	-1.14	6.88	6.97	2.60	0.226	1.77
tsg-lauge-koch	3079	1.00	1.27	1.73	2.14	1.59	0.670	1.24
sassie	1806045	-0.43	-1.63	4.79	5.06	2.85	0.320	2.04

▶ Table 2 is similar to Table 1 but considering only match-up pairs where RR=0 mm/h, 3< U_{10} <12 m/s, SST>5°C, distance to coast > 800 km.

Table 2: Statistics of ΔSSS (Satellite - *in situ*)

***in situ* database**	**#**	**Median**	**Mean**	**Std**	**RMS**	**IQR**	**r^2**	**Std***
argo	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
tsg-legos-dm	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
tsg-gosud-research-vessel	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
tsg-gosud-sailing-ship	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
tsg-samos	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
drifter	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
tsg-polarstern	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
saildrone	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
ices	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
tsg-amundsen	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
tsg-lauge-koch	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN
sassie	0	NaN	NaN	NaN	NaN	NaN	NaN	NaN

▶ Numerical values can be downloaded as csv files for Table 1 and Table 2.

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